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# Corner angle effects on capillary rise along curved interior corners

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Liquid management is becoming increasingly essential as spacecraft carry more liquid, which includes liquid propellants. Interior corners are commonly used as components in spacecraft liquid management systems to passively position or maintain liquid. Under microgravity, the capillary flow along the curved interior corner plays a significant role in the behavior of liquids in spacecraft. To manage and transport liquids in space efficiently, it requires a full understanding of capillary flows in interior corners. In this work, the influence of corner angle on capillary flows in curved interior corners is studied experimentally. A series of drop tower experiments to simulate the microgravity environment are conducted to discuss the movement of liquid in the interior corner. Experimental results show that the liquid moves faster as the corner angle decreases. This feature can be utilized to design the liquid transport devices and provide valuable advices for liquid management in space.

With the development of space technology, more and more spacecraft are entering space. The normal operation of satellites and space stations is inseparable from liquid propellants, cryogens, thermal fluids, and wastes<sup>1</sup>. The flow characteristics of liquid in space are quite different from those on the ground. Due to the decrease of gravity, surface tension forces dominate the transport and management of free surface flow. Surface tension forces are negligible in most engineering problems. Whereas, the location and orientation of liquid within vessels, conduits, etc. in the low-gravity environment of orbiting vehicles are strongly influenced by surface tension forces<sup>2</sup>.

In space, the interior corner is often used to passively position and/or control large length scale capillary-dominated liquid inventories, i.e., fuel/cryogen storage tanks<sup>3</sup>. It is a common construct employed in liquid management systems aboard spacecraft. Without gravity, spontaneous capillary flow along interior corners dominates the liquid behavior in spacecraft<sup>4</sup>. A quick and precise prediction of capillary flow along interior corners is necessary for liquid management processes under microgravity to control liquid effectively<sup>5,6</sup>.

Capillary flow research dates back to the 1960s, when Concus and Finn<sup>7</sup> proposed the Concus-Finn condition, a geometric wetting condition that corresponds to an underpressure in the liquid, resulting in capillary-driven flow into and along the interior corner<sup>8</sup>. Ayyaswamy et al.<sup>9</sup> solved the two-dimensional equations of motion for steady laminar flow along interior corners by the Galerkin boundary method. They also indicated that the half angle of the interior corner and the contact angle are two independent parameters that characterize the flow configuration. Lenormand and

Zarcone<sup>10</sup> proposed an approximate solution for the nonlinear diffusion equation of the flow along the corners by analogy with a nonlinear thermal problem. Dong and Chatzis<sup>11</sup> made improvements to the theory of Lenormand and Zarcone<sup>10</sup> that predicts the imbibition rate of a wetting liquid in the corners by introducing the dimensionless flow resistance  $\beta^{12}$  and improved the model accuracy. Romero and Yost<sup>13</sup> addressed the problem of capillary-driven flow in a V-shaped surface groove by solving a nonlinear diffusion equation for the liquid shape, which derived from mass conservation and Poiseuille flow conditions. A similarity transformation for this nonlinear equation was obtained, and the resulting ordinary differential equation was solved numerically for appropriate boundary conditions. Weislogel and Lichter<sup>5</sup> considered the spontaneous redistribution of fluid along an interior corner of a container due to capillary forces. By using the lubrication approximation, they were able to simplify the Navier-Stokes equations and solve the governing equation via similarity solution. After that, Weislogel's theory was applied to some complex containers<sup>4,14</sup>. Later, the problem of capillary flows along rounded interior corners was investigated theoretically and experimentally by Chen et al. 15 and Kang et al. 16. The gravity perpendicular and parallel to the channel axis were both taken into account in corner flows by Rame et al.<sup>17</sup>. The capillary flow in an asymmetric interior corner consisting of a straight vane and curved wall was investigated theoretically and experimentally by Jinghao Li<sup>18</sup> and Yongqiang Li<sup>19</sup>. Weislogel and McCraney<sup>20</sup> discovered a novel solution to the lubrication model for capillary liquid draining in straight and weakly curved channels.

So far, the previous studies on capillary flow mainly focus on straight interior corners (see Fig. 1). However, the curved interior corner (see Fig. 2)

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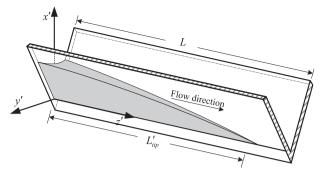


Fig. 1 | A liquid column in an isolated straight interior corner of angle  $2\alpha$ .

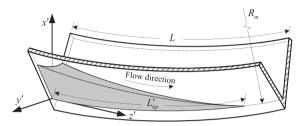


Fig. 2 | A liquid column in an isolated curved interior corner of angle 2α.

provides a further generalization. By analysis, the channel curvature and corner angle are seen as two important factors that influence the capillary flow in curved interior corners. The influence of channel curvature on the capillary flow in curved interior corners was investigated theoretically and experimentally by Wu et al. 6.

The present paper mainly discusses the influence of corner angle on capillary flow in a curved interior corner. An approach is presented for capillary flow along curved interior corners to predict the tip location. In this model, channel curvature effects have been taken into account. Furthermore, drop tower experiments are carried out to provide a microgravity environment. By setting a series of control experiments, the influence of corner angle on capillary flow in curved interior corners is investigated experimentally. Then, the experiments are compared with the theoretical calculations.

# Results and discussion

#### Drop tower experimental results

Several typical experimental frames of the drop tower tests are presented in Fig. 3. The free surface profiles are detected by the software GetData Graph Digitizer. GetData Graph Digitizer is a program to obtain original data from digitizing graphs and plots. In Fig. 4, free surface profiles for different time t are presented in the same figure. Due to the reflected light, the section of free surface profile close to the container's bottom is difficult to figure out. Consequently, this section is not shown in Fig. 4. The resolution of all experimental frames is 1125 × 680. Following calibration, 1 cm equates to 74.438 pixels. Therefore, the side length of each pixel is 0.134 mm. The free surface profiles in the images are very clear and no more than three pixels in size. The error is less than 0.402 mm. In addition, Fig. 4 confirms that the assumption of constant height H is valid for t > 1s. The measured constant heights  $H_{exp}$  of model 1, model 2, model 3, model 4, and model 5 are 2.5130 cm, 1.6716 cm, 1.3480 cm, 1.2160 cm, and 0.6935 cm. According to the relationship between the constant height  $H_{exp}$  and the mean curvature radius  $R_{H_{exp}}^{14}$ ,

$$R_{H_{exp}} = f \cdot H_{exp} \tag{1}$$

the experimental mean curvature radius  $R_{H_{cop}}$  can be obtained, where  $R_{H_{cop1}}=0.88$ cm,  $R_{H_{cop2}}=1.04$ cm,  $R_{H_{cop3}}=1.35$ cm,  $R_{H_{cop4}}=1.89$ cm,  $R_{H_{cop5}}=1.67$ cm. The mean curvature radii for the test models should be fixed. However, different test models have different mean curvature radii

 $R_{H_{\omega p}}$  in our experiments. This fact is contrary to this hypothesis. As will be discussed later, it has a direct influence on the results.

Figure 5a shows the measured tip location  $L_{tip}$  changes with t. Figure 5b shows the measured tip location  $L_{tip}$  changes with  $\sqrt{t}$ . At the start, the liquid's response to the sudden decrease in gravity is complex, and inertia plays a significant role at this stage. The liquid climbs rapidly, and what can be observed is the tip location  $L_{tip}$  grows linearly with t in this stage. About one second later, the effect of inertia disappears and that of viscous force becomes stronger. The liquid climbing speed decreases gradually.

#### Comparison of experimental and theoretical results

The experimental results and the theoretical results are compared in Fig. 6. Herein the mean curvature radius  $R_H$  is calculated by Eq. (10). Figure 6a shows the tip location  $L_{tip}$  changes with t. Figure 6b shows the tip location  $L_{tip}$  changes with  $\sqrt{t}$ . The theoretical results have the same trend as the experimental results. However, for test models 1 and 2, the theoretical results are larger than the experimental results. For test models 3, 4, and 5, the theoretical results are smaller than the experimental results. It is noted that, for test models 1 to 5, the mean curvature radii calculated by Eq. (10) have the same value  $R_H = 1.08$  cm. However,  $R_{H_{cup1}}$  and  $R_{H_{cup2}}$  are smaller than  $R_H$ . In addition,  $R_{H_{cup3}}$ ,  $R_{H_{cup4}}$  and  $R_{H_{cup5}}$  are larger than  $R_H$ .

Substituting  $R_H$  by experimental  $R_{H_{cop}}$ , the modified tip location  $L_{tip}$  is presented in Fig. 7. The modified results have a good agreement with the experimental results. For different corner angles, the root mean square error between experimental and theoretical results is 2.1 mm (test model 1), 1.6 mm (test model 2), 2.4 mm (test model 3), 2.9 mm (test model 4), and 4.2 mm (test model 5). Therefore, the mean curvature radius  $R_H$  has a direct influence on the tip location  $L_{tip}$ . By analysis, the precondition of Eq. (10) is that the bottom of the container should not have any dry spots<sup>21</sup>. In the experiment process, there is not a sufficient amount of liquid to cover the entire bottom because most of it flows into the corner. This is supposed to result in the error between  $R_H$  and  $R_H$ 

result in the error between  $R_H$  and  $R_{H_{cop}}^{\quad \ \ 6}$ . In addition, the machining error of the 3D printing, the residual acceleration, and the other disturbances can also affect the experimental results. Emphasizing that these potential causes are just hypotheses and require validation with additional data.

The tip location  $L_{tip}$  grows linearly with  $\sqrt{t}$  for t > 1s from Fig. 7b.  $grad(L_{tip})$  is defined as,

$$grad(L_{tip}) = \frac{\Delta L_{tip}}{\Delta \sqrt{t}} \tag{2}$$

and it represents the gradient of  $L_{tip} \sim \sqrt{t}$  curve. The relationship between the gradient  $\operatorname{grad}(L_{tip})$  and the corner angle  $\alpha$  is shown in Fig. 8. The gradient  $\operatorname{grad}(L_{tip})$  decreases as the corner angle  $\alpha$  increases. As a result, when the angle is infinitely close to 0, there should be a fast climb velocity, but the flow rate would be very small and therefore have no practical significance for engineering, as shown by others<sup>8,22</sup>. To apply the conclusion, further optimization research is required.

## **Concluding remarks**

The previous study<sup>6</sup> has investigated the effect of channel curvature on capillary flow in curved interior corners theoretically and experimentally. In this paper, corner angle as another factor that has great influence on the capillary flow along curved interior corners is investigated. A series of microgravity drop tower experiments are operated at the National Microgravity Lab of Chinese Academy of Sciences. The experimental results are compared with the theoretical results that were obtained from the theoretical method introduced in ref. 6. The experimental results agree well with the theoretical results. Both experimental results and theoretical results show that the liquid rises faster as the corner angle decreases. This conclusion can be utilized to design and optimize the liquid management devices on board spacecraft. For example, when the liquid propellant in the fuel tank is disturbed and deviates from the outlet, we hope that the

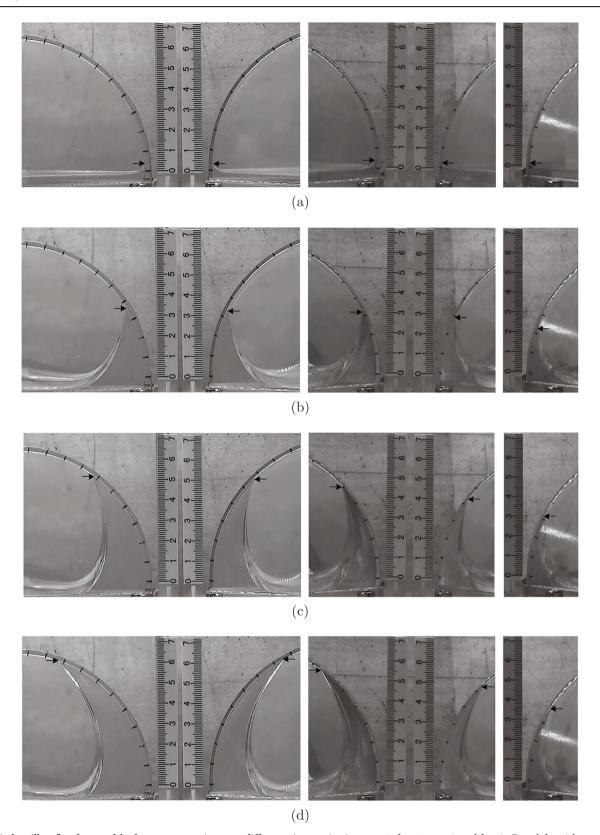


Fig. 3 | Typical capillary flow frames of the drop tower experiments at different microgravity time. a t = 0s, b t = 1s, c t = 2s and d t = 3s. From left to right are test model 1, 2, 3, 4, and 5. The arrow denotes the tip location of the meniscus in the corner.

propellant can return to the outlet port as quickly as possible to provide a continuous flow of liquid propellant for the thrust chamber. Therefore, the climbing velocity of capillary flow along the curved interior corners should be fast, which means that the designers should choose interior corners with small corner angles.

# Methods

# Theoretical analysis

The gravity effects on the free surface flow become weak in space; instead, the surface tension plays an important role. An isolated curved interior corner under microgravity is considered in this section. As depicted in Fig. 2,

**Fig. 4** | The free surface profiles of different test models. The free surface profiles of (a) model 1, **b** model 2, **c** model 3, **d** model 4 and **e** model 5 for times t = 0s, 0.5s, 1s, 1.5s, 2s, 2.5s, 3s, and 3.5s. The dotted lines represent the free surface profiles and the solid lines represent the bottoms of the corners. The error of each free surface profiles is less than 0.4mm.

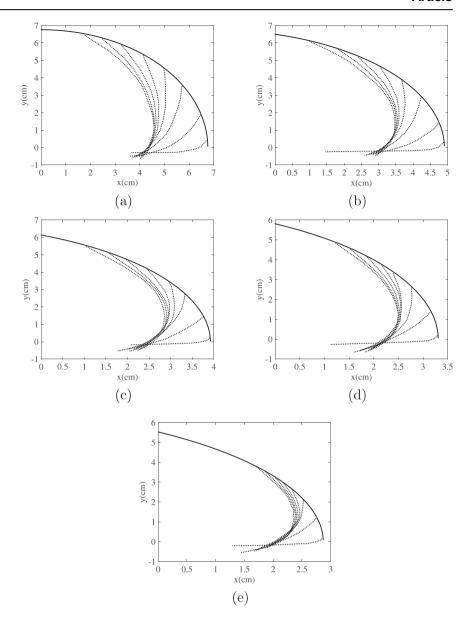
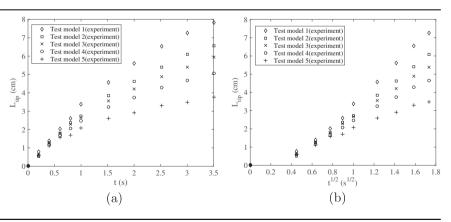


Fig. 5 | The comparison of experimental results with different corner angle  $\alpha$ . a Tip location  $L_{tip}$  as a function of t. b Tip location  $L_{tip}$  as a function of  $t^{1/2}$ .



the curved interior corner of angle  $2\alpha$  is partially filled with liquid, making contact angle  $\theta$  with the solid surface and satisfying the Concus-Finn condition,  $\theta \le (\pi/2 - \alpha)$ . The channel curvature radius  $R_m$  which refers to the curvature radius of the curved flow path, keeps constant. Due to the surface tension, the slender liquid column proceeds along the corner to an infinite distance. The flow in the interior corner is assumed to

be viscous, incompressible, isothermal, and laminar. Due to the flow direction is nearly parallel to the contact line, the contact angle  $\theta$  can be regarded as a constant without considering the hysteresis effect. In addition, there exists a constant height at z=0 for all t, namely H= constant (see Fig. 2). Its validity is verified experimentally by Weislogel et al.  $^5$  and Wu et al.  $^6$ .

Fig. 6 | The comparison between measured tip location and theoretical tip location with different corner angle  $\alpha$ . a Tip location  $L_{tip}$  as a function of t. b Tip location  $L_{tip}$  as a function of  $t^{1/2}$ .

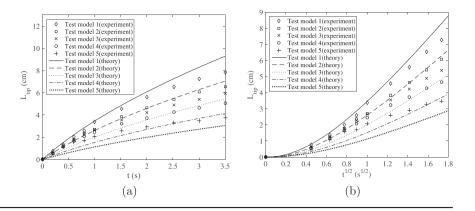
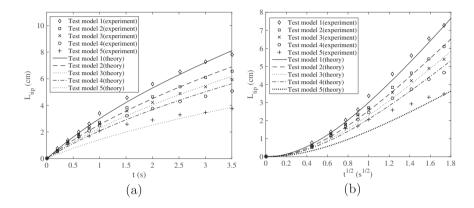
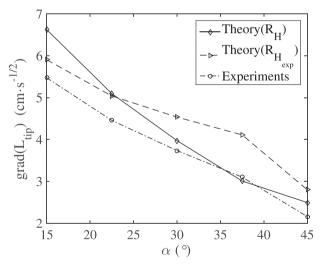


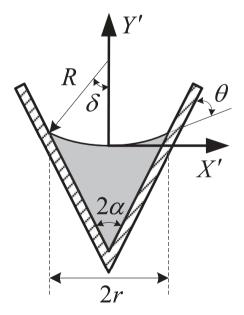
Fig. 7 | The comparison between measured tip location and modified theoretical tip location with different corner angle  $\alpha$ . a Tip location  $L_{tip}$  as a function of t. b Tip location  $L_{tip}$  as a function of  $t^{1/2}$ .





**Fig. 8** | The influence of the corner angle  $\alpha$  on the capillary flows along curved interior corners.

In the curved interior corners, not only the surface tension but also the centrifugal force affect the free surface flow as introduced in ref. 20. The centrifugal force is caused by the curve motion of the flow, and conversely, it affects the capillary flow. Figure 9 shows the cross-section of the curved interior corner in Fig. 2. The free surface is a meniscus without gravity. Neglecting viscous normal stresses, there is a direct relationship between the free surface shape and the pressure difference across the free surface



**Fig. 9** | **Cross-section of an isolated interior corner.** The centrifugal force acts on the liquid in the negative *y*-direction.

according to the Young-Laplace equation,

$$P_a - P = \frac{2\sigma}{R} \tag{3}$$



Fig. 10 | Test models installed on the experimental platform of the drop capsule.

where  $P_a$  is the ambient pressure, P is the liquid pressure,  $\sigma$  is the surface tension and R is the mean curvature radius of the free surface. If centrifugal force acts on the free surface, it will change the shape of the free surface. As a result, the free surface shape affects the capillary flow in the curved interior corner.

At the lowest point of the free surface, a Cartesian coordinate is created. (see Fig. 9). The centrifugal force acts on the liquid in the negative *y*-direction. Due to  $H/R_m \ll 1$ , the centrifugal acceleration *g* can be considered uniform in the x-y plane,

$$g = \frac{\bar{w}^2}{R_m} \tag{4}$$

herein  $\bar{w}$  is the average velocity of the cross-section which perpendicular to flow direction.

The free surface y(x) is determined by both surface tension and centrifugal force. The normalized differential equation of free surface can be expressed by(see<sup>6</sup> for more details),

$$Bo \cdot Y + \cos(\theta + \alpha) - Bo \cdot \int_{0}^{1} Y dX = \frac{Y_{XX}}{(1 + Y_{X}^{2})^{\frac{3}{2}}}$$
 (5)

subject to the Y(0) = 0 and  $Y_X(0) = 0$ , where X = x/r, Y = y/r, r is the half width of free surface,  $\theta$  is the contact angle, Bo is Bond number defined by  $Bo = \rho g r^2 / \sigma$ .

Eq. (5) is a second order integro-differential equation. The powerseries method<sup>23</sup>, iterative method<sup>24</sup>, shooting method<sup>25</sup> and Runge-Kutta method<sup>26</sup> and so on were used to solve this equation. These methods share some drawbacks, such as poor convergence, dependence on initial values, and instability. The inevitable result of this is long calculation times and sudden calculation interruptions. Here an approximation modeling method based on an improved radial basis function<sup>27</sup> is used to replace the free surface governing equation Eq. (5). Approximation model, also known as surrogate model or metamodel, provides a substitute for and is used in lieu of this real-world function f(t) with a small price. This approximation model is approximately equivalent to Eq. (5) through data training, but is much easier to solve.

Combining the approximation model, the tip location  $L_{tip}$  can be obtained (see<sup>6</sup> for more details),

$$L_{tip} = \int_{0}^{t} 0.8510 \sqrt{\frac{(1 + 0.286Bo_{R_{H}}) \cdot G \cdot R_{H}}{f \cdot t}} dt$$
 (6)

where  $Bo_{R_H}=\rho gR_H^2/f\sigma$  is the Bond number based on f and mean curvature radius  $R_H$ . The parameter f can be denoted as,

$$f = \frac{\sin \alpha}{\cos \theta - \sin \alpha} \tag{7}$$

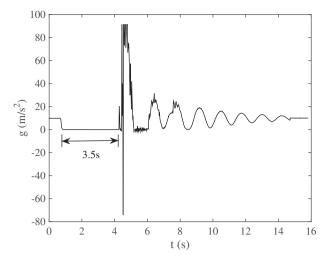


Fig. 11 | The acceleration curve recorded by the accelerometer preset in the drop capsule.

The parameter *G* can be denoted as,

$$G = \frac{\sigma F_i \sin^2 \alpha}{\mu f} \tag{8}$$

where  $F_i$  is the friction factor defined by Weislogel and Lichter<sup>5</sup>.

#### Experimental setup and procedure

To investigate the influence of corner angle  $\alpha$  on capillary flow along curved interior corners, a group of test models (see Fig. 10) with different corner angles  $\alpha$  are fabricated by 3D printing technology. To get a better observation of the capillary flow, these models are made of transparent resin and polished.

Usually capillary phenomena can be observed only at a small scale under ground conditions. Capillary length  $l^{*8}$  defined as,

$$l = \sqrt{\frac{\sigma}{\rho g}} \tag{9}$$

is an indication to judge whether the capillary phenomenon is obvious or not. It is a characteristic length scale for an interface between two fluids that is subject both to gravity and to surface tensions. For pure water and air at 20 °C, the capillary length takes the value 2.71mm. When the characteristic length is much less than the capillary length, the surface tension dominates the capillary flow, and the gravity can be neglected, and vice versa.

However, the capillary length under microgravity can be orders of magnitude larger than that on the ground. As a result, the test models of capillary flows under microgravity can be orders of magnitude larger than their normal-gravity counterparts. In addition, large-scale capillary flows are easier to visualize and can be tracked over long distances<sup>5</sup>. Within the limitations of the experimental installation platform, the test model sizes should be as large as possible.

A short-term microgravity experimental environment can be provided at a much lower cost by using the drop tower. The microgravity environment is accessed by using the drop tower facility at the National Microgravity Lab of Chinese Academy of Sciences for capillary flow experiments in this study. To minimize the effect of air resistance on the experiment, a dual-drop capsule system is employed, and a microgravity environment of  $10^{-5}g_0$  can be reached. Figure 11 shows the acceleration curve recorded by the accelerometer preset in the drop capsule. As can be seen from the curve, the entire microgravity time is about 3.5s.

Table 1 | Liquid properties of the distilled water, ethanol and silicone oil

Liquid	v (cSt)	$\sigma$ (N · m <sup>-1</sup> )	θ (°)	$ ho$ (kg $\cdot$ m <sup>-3</sup> )
Distilled water	1	0.072	89.66	1000
Ethanol	2	0.0227	0	789
PDMS	10	0.0201	0	935

Table 2 | Geometry parameters of the capillary flow test models

Model	a (°)	d (mm)
1	15	70
2	22.5	53.1
3	30	45.3
4	37.5	41.7
5	45	40.6

These test models have the same channel curvature  $R_m^{-1} = 14.79 \text{m}^{-1}$ .

In this study, distilled water, ethanol, and silicone oil are selected as the alternative working fluids, and they are often used in microgravity experiments. Their surface tensions, viscosities, and densities are measured specifically for this research work using standard laboratory procedures (see Table 1).

The distilled water and ethanol can be better blended with the dye to facilitate observation. However, the distilled water climbs fast due to its large surface tension. It needs a high-speed camera to record the experiments; otherwise, it will bring great errors. In addition, the distilled water reaches the top of the test model too quickly, and it's a waste of the precious microgravity time. In the compatibility test, it is found that cracking occurred on the surface of the resin after being immersed in ethanol. The silicone oil has the characteristics of safety, non-toxicity, good compatibility, and optional viscosity. Therefore, the 10 cSt silicone oil is chosen as the experimental fluid in this experiment.

The factors affecting the capillary flow in a curved interior corner are the geometry of the model and the properties of the liquid. It can be further subdivided into channel curvature  $R_m^{-1}$ , corner angle  $\alpha$ , mean curvature radius  $R_H$ , liquid viscosity  $\nu$  and surface tension  $\sigma$ .

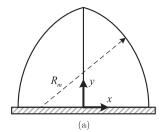
The channel curvature  $R_m^{-1}$  and corner angle  $\alpha$  are determined by the geometry of the test model. The viscosity  $\nu$ , surface tension  $\sigma$  and contact angle  $\alpha$  are determined by the properties of the liquid. The mean curvature radius  $R_H$  is determined both by the geometry and contact angle  $\alpha$ . In order to study the influence of corner angle  $\alpha$  on the capillary flow, a set of test models with different corner angles are set up. In order to make the corner angle  $\alpha$  the only variable affecting the capillary flow, the other factors should be fixed. Therefore, this set of test models has the same channel curvature  $R_m^{-1}$ , and the same working liquid is used. In addition, the mean curvature radius  $R_H$  should also be fixed.

By using the method of de Lazzer et al.<sup>21</sup>, the mean curvature radius  $R_H$  can be determined below<sup>14</sup>,

$$R_{H} = \frac{L_{p} \cos \theta}{2\Sigma} \left( 1 - \sqrt{1 - \frac{4A_{c}\Sigma}{L_{p}^{2} \cos^{2}\theta}} \right)$$
 (10)

herein  $L_P$  is the perimeter of cross-section,  $A_c$  is the cross-sectional area,  $\Sigma = 0.5 \sum_{j=1}^{n} k_j F_{Anj}, F_{Anj} = \frac{\cos \theta \sin \delta_j}{\sin \alpha_i} - \delta_j.$ 

According to Eq. (10), we can choose appropriate geometrical parameters to make this set of test models have the same mean curvature radius  $R_H$ . The geometrical parameters of the test models are listed in Table 2. The



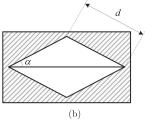


Fig. 12 | Different views of the capillary flow test model. a Front view. b Top view.

corner angle  $\alpha$  increases from model 1 to model 5. Figure 12 shows the typical top view and front view of these models.

Taking test model 1 as an example, it can be estimated that 10 cSt silicone oil can climb up to the top of the test model within 3.5 s according to Eq. (6). The purpose of fully utilizing the available microgravity time is achieved, which is also the reason for choosing 10 cSt silicone oil as the testing liquid.

A prescribed amount of silicone oil is injected into the bottom of the test models prior to the experiment. Before releasing the drop capsule, the test liquid stays at the bottom of the test models due to gravity. Upon release, the gravity effect disappears and surface tension becomes the dominant force. Meanwhile, the liquid begins to flow into the corner. These experiments are recorded by cameras with frame rates up to 50 frames per second.

## **Data availability**

The data that support the findings of this study are available from the corresponding author upon reasonable request.

# Code availability

Not applicable.

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#### **Author contributions**

Z. Wu, B. Wu and Y. Zhang wrote the main manuscript text. G. Li and C. J conducted the microgravity experiments. Y. Chen and K. Li supervised the theoretical methods and the experiments. All authors reviewed the manuscript.

#### Competing interests

The authors declare no competing interests.

#### **Additional information**

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