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Monitoring and predicting cotton leaf diseases using deep learning approaches and mathematical models

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Cotton, the backbone of global textile production, demands sustainable agricultural practices to ensure fiber, food, and environmental security. Cotton crop play an essential role in farming economies; however, production is sometimes affected by various diseases that harm production. We proposed a methodology that uses formal modeling and verification for requirements confirmation to improve the monitoring and detection of cotton crop diseases. The correct information and requirements about disease symptoms can improve disease monitoring and prediction. The Temporal Logic of Action (TLA+) is used to construct a mathematical model to verify requirements by providing disease symptoms and then model checking to ensure correctness properties. Using model checking in TLA+ ensures the reliability and correctness of disease symptom detection. We consequently used deep learning models to predict cotton diseases, i.e., Aphids, Armyworms, Bacterial Blight, Powdery Mildew, Target Spot, and Healthy leaf. Our results show that the Convolutional Neural Network (CNN) model achieved an overall accuracy of 98.7% with class-specific accuracy ranging from with F1-scores across all classes (e.g., 0.90 for Powdery Mildew and 0.87 for Army Worm).

Keywords Cotton crop, Monitoring, Prediction, Requirement verification, Temporal logic, Temporal logic of actions (TLA+), Formal modeling, Formal verification, Correctness, Reliability, Deep learning (DL), Convolutional neural network (CNN), Long short term memory (LSTM), Recurrent neural network (RNN)

In Pakistan, the agricultural sector is the backbone of the economy, and it relies on producing important crops such as cotton, wheat, rice and corn, which are influenced by strategic and environmental factors that determine yield production. Cotton is an important cash crop that supports the livelihoods of almost 150 million individuals across 75 countries. Pakistan is the fifth-largest cotton producer, contributing 5% to global production and supporting 1.7 million farmers¹. Cotton contributes significantly to Pakistan's economy, using 50% of its industrial workforce and 60% of its exports. Despite its importance, production has declined by 27.2% due to climate change, production costs, poor seed quality, and cotton crop diseases. Climate change, with uneven rainfall and temperature changes, has increased pests like whiteflies and pink bollworms, decreasing cotton yields¹.

Remote sensing and machine learning monitor crop productivity, facilitating extensive and continuous observation of agricultural practices. This method² enables the detection of crop and growth trends over agricultural areas, improving agriculture to maximize land use and resource efficiency. Nazeer et al.³ used a deep learning model that identifies disease susceptibility levels, enabling instantaneous actions to identify disease transmission. A deep learning model is needed to assess susceptibility levels to cotton leaf curl disease in some regions of cotton production, thus contributing to a proactive method for crop management.

Deep learning improved agricultural practices, crop classification, and health evaluation. Shahid et al. used an ensemble of deep learning models, achieving 98% accuracy in predicting cotton crops from other plants via refined analysis. Technological progress and advanced computational models have acquired significant developments in the agricultural sector. Cotton is vital among numerous crops due to its use in different industries. However, cotton crops are susceptible to diseases, which can significantly impact overall yield and agricultural crop improvement. Thrips are small, slim insects with fringed wings that feed on plant sap, causing damage by creating stippling and silvering on leaves. Figure 1 presents the proposed approach for this work.

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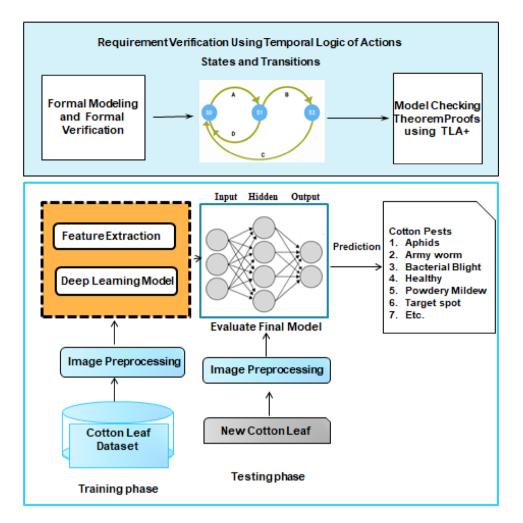


Fig. 1. Proposed approach for this work.

Jassids, tiny greenish insects; Whiteflies, small white insects, feed on sap, excrete honeydew, and transmit plant viruses⁷; control methods include insecticides and predatory insects. Pink Bollworm larvae damage cotton bolls, reducing yield; control involves using Bt cotton and insecticides⁸. The work⁹ presents machine learning (ML) for accurate cotton yield prediction, using weekly weather as input. Key predictors included minimum temperature and relative humidity. Amani and Marinello¹⁰ proposes a deep-learning model to optimize cotton cultivation soil parameters and agricultural variables. Analyzing 13 factors reduces costs and environmental impact while enhancing productivity.

Monitoring cotton crop diseases is critical for supporting sustainable agricultural practices and safeguarding farmers' livelihoods. Diseases such as Aphids, Army worm, and Bacterial Blight threaten crop yield and quality. Effective detection and management strategies can play a key role in mitigating these risks, minimizing economic losses, and ensuring the reliability of cotton farming approaches.

Problem statement

Detecting cotton crop diseases is essential to mitigate yield losses that affect the agricultural economy and challenges to the agriculture sector. Existing methods for disease detection provide predictions and the monitoring of diseases; however, their reliability depends on verifying their requirements. The problem is to verify the requirements for ensuring correctness properties to improve reliability—a deep learning model for predicting cotton crop diseases based on images dataset.

Research objectives and research question

The objectives of this proposed approach are as follows:

- Verify the correctness and reliability using TLA+, a robust formal specification and modeling language.
- Predict cotton crop diseases using a deep learning algorithm based on an image dataset.
- Evaluations of the Deep Learning model are needed to establish its effectiveness in accurately predicting cotton crop diseases.
- Facilitate informed decision-making for agronomists and farmers by understanding cotton crop health and enabling crop management practices.

- R. Q. 1. How does Temporal logic of action (TLA+) improve correctness and reliability using formal modeling and verification methods to identify cotton crop diseases?
- R. Q. 2. How can deep learning models, Convolutional Neural Networks (CNN), be used for early and accurate prediction of cotton diseases based on image data?

Literature review

Machine learning and deep learning advancements have transformed cotton agriculture by solving farmers' challenges. Da Silva Andrea et al. ¹¹ presented a remote sensing and machine learning framework for estimating plant height in cotton fields. This method improves monitoring capabilities, providing efficient growth management in agriculture sectors. Feng et al. ¹² proposed a technique for detecting and counting cotton saplings with UAV multispectral images. The technology facilitates crop evaluation, enabling farmers to make decisions regarding resource distribution throughout the growth phases.

The classification of cotton leaf diseases has significantly advanced due to deep learning methodologies, essential for disease control, as these diseases lessen yields by 20% each year. A robust approach to cotton plant disease detection using an improved Deep Convolutional Neural Network, achieving an accuracy of 97.98% on a dataset of 2293 images^{13,14}. It explores the impact of data splits, pooling layers, and epoch sizes, outperforming prior methods in accuracy and efficiency. A comprehensive review of machine learning and deep learning techniques for crop pest detection and classification used RF, SVM, CNN, and DBN. It demonstrates their potential to enhance crop productivity and protection by enabling automated, large-scale monitoring with reduced human error and effort¹⁵.

The glass-box approach, the Explainable Boosting Machine (EBM), is used for cotton yield prediction across the continental United States¹⁶. Key findings focus on precipitation, EVI, and LAI as dominant features, contributing 78% to the model's feature importance, followed by pairwise feature interactions (16%) and static features (6%).

AI-driven hydroponics system using an Extra Convolutional Neural Network optimized with the Levy Flight Carnivorous Plant algorithm (ExCNN-LFCP) and an IoT cloud server. The system automates and optimizes hydroponic farming by precisely managing environmental parameters, improving effectiveness and sustainability. Sensor data is processed to predict optimal conditions, enabling remote monitoring and centralized control. Experimental results show superior performance, achieving 99.1% accuracy and 97.3% recall¹⁷. An automated black gram plant disease (BPLD) detection system, ITL-CHB, using an Improved Inception-V3 Transfer Learning model optimized with the Crossover Honey Badger (CHB) algorithm. The system enhances disease classification accuracy using data augmentation techniques to address data imbalance. Feature extraction is performed using the pre-trained Inception-V3 model, optimized through CHB. Performance evaluation demonstrates 98% accuracy, outperforming traditional methods like SVM, EfficientNet, ResNet-50, and CNN¹⁸.

Big data and transfer learning methodologies have improved the scalability of cotton crop surveillance. Stephen et al. 19 demonstrated a big-data-based cotton plant monitoring system using pre-trained CNN architectures to enhance plant health monitoring. MobileNetV3Large outperformed ResNet18, GoogLeNet, and InceptionV3, achieving 93.9% accuracy, 96.12% specificity, and 97.48% precision. The system classifies 11 cotton plant regions and provides farmers with an understanding of harvesting, yield, and plant health, including wildflower detection and disease identification. Smartphone image collection and a smart application ensure practical, real-world usability for precision agriculture. Aarthi et al. 20 illustrated a DenseNet-121 pre-trained model with transfer learning to detect cotton leaf diseases, achieving a classification accuracy of 91%. Compared to traditional CNN methods, this approach improves disease detection efficiency and offers farmers a scalable approach to monitoring crop health. The model supports yield prediction, resource management, and crop protection decision-making.

This work²¹ uses machine learning techniques to classify surface soil types and evaluate soil physicochemical properties using spectroradiometer and satellite imagery. Applied in Phulambri Tehsil, Maharashtra, models like PLSR, SVM, and SAM achieved 95% classification accuracy for three major soil classes. These findings demonstrate the potential of machine learning in precision farming, enabling efficient soil management and improved agricultural productivity. The advancement of artificial intelligence has transformed different sectors, with agriculture becoming a vital sector experiencing harmful changes²².

Ashapure et al.²³ review the applications of machine learning in agriculture, presenting its role in addressing challenges like resource limitations and climate change. Key areas include soil parameter prediction, crop yield forecasting, disease and weed detection, and livestock management through IoT-enabled systems.

Livieris et al.²⁴ presented a multiple-input neural network model for cotton yield prediction, using soil, cultivation, and yield management data processed individually. The architecture efficiently handles mixed data, reduces overfitting, and offers flexibility with low computational cost. Tested on data from cotton farms in Central Greece, the model outperformed traditional and state-of-the-art neural network models, demonstrating its effectiveness in improving yield forecasting and benefiting agricultural economics. This work²⁵ includes robotic capsicum harvesting using YOLOv8s for detection (mAP: 0.967) and YOLOv8s-seg for peduncle detection (mAP: 0.790). The Real Sense D455 camera achieved precise localization, while a tracking algorithm attained 94.1% accuracy. An Android app enhanced usability with performance and a 95% success rate, showcasing the potential for efficient agricultural automation. Wang et al.²⁶ propose the White Bolls Index (WBI) for automatic cotton mapping, achieving over 82% accuracy across four regions. WBI distinguishes cotton based on boll opening intensity and identifies the onset of the boll opening stage using Sentinel-2 time series data, offering a scalable and efficient solution for crop monitoring.

This research introduces an ontology-based knowledge map model for dynamically managing and using data mining results in crop farming. The proposed system²⁷ architecture for knowledge modeling, extraction, and exploitation has been implemented for crop management, demonstrating its effectiveness and potential

for broader applications in agriculture. Haider et al.²⁸ presents a crowd-sourced platform to gather agricultural knowledge and data for wheat disease identification. By combining Decision Trees (DT) and deep learning models like CNNs and validating results with domain experts, the approach achieved significant accuracy improvements: DT (28.5%) and CNN (4.3%, reaching 97.2%).

Narcisse et al.²⁹demonstrated the development of *ontoSYSPARCOTCI*, a domain ontology for cotton plant health surveillance in Côte d'Ivoire, addressing pest challenges and enhancing systematic monitoring. Using the NeOn methodology, the ontology integrates resources and scenarios for structured knowledge representation. Results include a conceptual model in UP/UML and a hierarchy of concepts in OWL created with Protégé, enabling semantic reasoning and knowledge sharing for improved pest management.

The formal method checks the model's correctness and reliability using formal verification techniques. Model checking is the technique for system verification. The model verifies whether the property is the variable of the system or not. Formal verification will help check the correctness of the proposed design based on its correctness properties. TLA+is a language used in the formal specification of concurrent and distributed systems, which involves verifying and checking the correctness³⁰.

Gaps in previous research

Previous research on cotton leaf disease detection has made significant strides using deep learning models such as Deep CNN (97.98% accuracy), MobileNetV3Large (93.9%), and YOLOv8s. However, key gaps remain. Previous studies rely on small or imbalanced datasets, lack generalization across diverse environments, and often neglect real-world deployment challenges due to high computational costs. Moreover, formal verification methods ensure model reliability and availability in critical agricultural real-world applications. Our work addresses these issues by using a robust, different dataset, optimizing computational efficiency, and incorporating formal verification steps.

State of the art Formal modelling and verification

Formal modeling and verification based on mathematics, logical construction, and formal language define and verify requirements that confirm the specifications. Formal modeling and verification are essential in safety-critical systems, offering a systematic mathematical framework that ensures correctness and reliability.

Formal verification is rigorous and ensures the correctness properties of the system's safety. Formal methods are used in requirement verification and design to safeguard correctness properties using state, transition, proof obligations, theorem proving and inductive logic³¹. A model provides a basis to improve and verify the system rigorously, and it is also significant in safeguarding the system's correctness. It takes input and systemically checks whether the system holds the correct safety properties.

Formal modeling involves the development of mathematical verification of a system's architecture and dynamics, enabling potential states and transitions that the system experiences. The method eliminates ambiguities in specifications and ensures the system's functionality corresponds with its requirements. Verification involves rigorously demonstrating that the model complies with fundamental qualities, such as safety and liveness, which ensure that the system avoids undesirable situations and reliably executes its intended activities.

This work systematically verifies that these criteria are maintained across scenarios using formal verification techniques like theorem proving and model checking. The model checker systematically inspects the model's state space, ensuring designated properties, such as invariants or temporal properties, are designated. A Formal verification and modeling technique helps detect undetected errors in conventional testing methods.

Temporal logic of actions (TLA+)

Temporal logic of action (TLA+) is a formal specification and modeling language based on temporal logic and mathematical foundation. Leslie Lamport, TLA+, created a software development tool to ensure the correctness of concurrent and distributed systems³². It uses mathematical logic to describe system behaviour and allows designers to formulate and verify their design methods. Formal modeling and verification with the TLA+ and PlusCal language are effective measures for ensuring that the concurrent and distributed systems are correct. TLA+ is a language used for modeling behaviour, and the implementation process is more accessible than Pluscal. Formal verification via model checking ensures that a system verifies its requirements³². Figure 2 presents Workflow diagram for Temporal logic of action.

Model checking

Model checking^{35–41}is one of the most practical formal approaches for systematic, automatic, and exhaustive verification. "It is a computer-assisted method for analyzing dynamical systems that state-transition systems can model"³⁵ A mathematical model of the system is formed, and a comprehensive evaluation of the model is executed. It comprises checking all states and transitions in the model, i.e., an exhaustive model analysis. It generates an abstract demonstration of a system with all the possible transitions and states.

The correctness property of the model is verified through model-checking methods. The model takes input and systemically checks whether the system safeguards the system's property. It is used to verify projects, i.e., the verification of software systems for *spacecraft*, *nuclear reactors*, *aeroplanes*, *subway trains*, and *satellites*. Its goal is to improve the reliability of verification by checking correctness properties.

"Model checking is an automated technique that, given a finite-state model of a system and a formal property, systematically checks whether this property holds for (a given state in) that model. Model-based verification techniques are based on models describing the possible system behaviour mathematically, precisely and unambiguously. The accurate modeling of systems leads to the identification of incompleteness, ambiguities, and inconsistencies in informal system specifications. A system model is accompanied by algorithms that

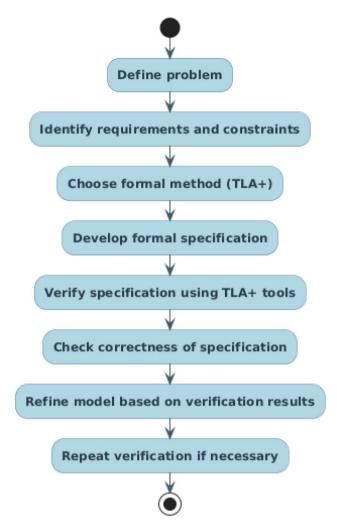


Fig. 2. Workflow diagram for temporal logic of action.

systematically explore all states of the system model. It provides the basis for verification techniques ranging from an exhaustive exploration (i.e. model checking) to experiments with a restrictive set of scenarios in the model (i.e. simulation), or in reality (i.e. testing)⁴³⁶.

Model checking uses temporal logic, i.e. linear-time temporal logic (LTL) $^{44-46}$ and computation-tree temporal logic (CTL) 42,43 for stating, checking, and verifying behavioural properties. Model checking is the mathematical verification of a system, and its result involves an exhaustive systematic investigation of the mathematical model 47 .

Correctness property

Safety property is correctness property. Correctness properties provide detailed system verification. The safety property is an invariant that asserts that "something bad never happens, that an acceptable state of affairs is maintained." Calegari and $Szasz^{48}$ have defined safety property " $S = \{a1, a2,..., an\}$ as a deterministic process that asserts that any trace, including actions in the alphabet of S, is accepted by S. ERROR conditions are like exceptions which state what is not required, as in complex systems we specify safety properties by directly stating what is required." According to "a safety property is a property that can specified by a safety formula of the form $\Box p$ (i.e. temporal operator \Box meaning always). This formula states that the property p holds throughout the computation".

Justification for TLA+ model

TLA+ selected for formal modeling and verification due to its strength in specifying and reasoning about system behaviours over time, particularly in concurrent or reactive systems like automated disease detection pipelines. TLA+ allows us to rigorously define correctness properties—such as consistency, safety, and liveness- which are critical when deploying models in real agricultural environments. By applying model checking through TLA+, we systematically explore all possible states and transitions, ensuring that the detection process adheres to predefined rules under varying conditions. This approach enhances the reliability and robustness of our system by preemptively identifying potential design flaws before real-world deployment.

Convolutional neural network (CNN)

Zohar and Amir⁵⁰ thoroughly studied the coefficients and other CNN structures used in computer vision. CNN, a deep learning model, can solve problems involving grid-like data structures such as images and videos⁵¹. An essential part of a CNN consists of kernels, strides, padding, pooling, and flattening.

The convolutional filter kernel is essential for extracting features from input data in convolutional neural networks. The convolution operation takes a kernel and slides it across the input by conducting element-wise multiplication and summing the outputs. The feature maps capture the fundamental patterns via edges or textures, which help the network acquire hierarchical representations from the input. The movement spacing in CNNs, determined by the stride parameter, is the kernel's distance when it moves over the input during the convolution process. Upon the prolongation of each step, the spatial down-sampling appears, decreasing the size of the output feature map, which, in turn, enhances calculation speed. Reducing the length of each step maintains the spatial details, resulting in larger maps of distinctive features. The selection of stride directly affects the balance between spatial resolution and computational workload, affecting the network's capacity to identify complex patterns in the input.

In CNNs, padding adds extra pixels around the input data, usually with zero values. The main objective of padding is to avoid spatial dimension loss following convolution. It ensures that the convolution process considers the entire input space, which is significant at the corners where information could be lost. Padding is critical for preserving spatial information and maximizing the features for the overall performance and effectiveness of the network. Pooling layers in CNNs is vital for reducing the size of the feature maps produced by convolutional layers. Max pooling and average pooling are prevalent methods for selecting average values from a cluster of adjacent pixels. Combining reduces complexity while maintaining translation invariance and preserving crucial information in feature maps. By pooling, learners discard less essential details and concentrate on the critical attributes to achieve more effective hierarchical feature learning. The following stages of the convolutional layer and the pooling layer result in the output matrix flattened into a linear vector with several dimensions. Those low-dimensional vectors are put in fully connected networks and converted to a more familiar neural network structure. The flattened layer is fundamental for the operation of CNNs because it provides a format for the spatial features of the acquired image, more processing, and making decisions. It links the convolutional, fully connected layers, thus ensuring that when the network learns subtle patterns and correlations from the input information, it will identify complex tasks like image classification.

The convolution operation is a fundamental aspect of Convolutional Neural Networks (CNNs) and is crucial in feature extraction. Mathematically, the equation represents the sliding of a filter (or kernel) over the input image or previous feature map. The kernel weights are multiplied by the corresponding pixel values in the receptive field, and the sum of these products is computed for each kernel position. This sum is then passed through an activation function, often a nonlinear function such as ReLU or Sigmoid, to introduce non-linearity into the network. The result of this operation is a feature map that captures spatial hierarchies of the input data, helping the network to detect patterns such as edges, textures, and shapes in images. Adding a bias term further enhances the model's flexibility by shifting the activation, allowing the network to fit the data better.

$$y_{i,j}^{l} = \sigma \left(\sum_{m=0}^{k-1} \sum_{n=0}^{k-1} w_{m.n}^{l} \cdot x_{i+m,j+n}^{l-1} + b^{l} \right) \dots Convolution operation$$

Batch normalization (BN) is a technique employed to accelerate the training of deep neural networks by mitigating internal covariate shift, which refers to the changes in the distribution of layer inputs during training. The equation for batch normalization normalizes the input data by subtracting the batch mean and dividing it by the batch standard deviation, effectively standardizing the activations within each mini-batch. This step ensures that the network learns with consistent data distribution, reducing the chances of vanishing or exploding gradients. After normalization, the data is scaled and shifted by learned parameters γ (gamma) and β (beta), allowing the model to recover any necessary shifts or scaling that might have been lost in the normalization process. This operation stabilizes the training process and enables faster convergence, often resulting in improved model performance.

$$x = \frac{x - u}{\sqrt{\sigma^2 + \delta}}, \ y = \gamma \hat{x} + \beta$$
.....Batch Normalization

Max pooling is a downsampling operation commonly used in CNNs to reduce the spatial dimensions of the feature maps while retaining the essential information. The equation for max pooling describes the process of selecting the maximum value from each patch of the feature map, typically within a fixed-size window (e.g., 2×2 or 3×3). The primary goal of max pooling is to introduce spatial invariance by reducing the impact of small translations, rotations, and distortions in the input data. This operation reduces the computational burden of the network and helps mitigate overfitting by forcing the network to focus on the most prominent features rather than being sensitive to noise or minor variations. The downsampling effect achieved by max pooling enables deeper networks by reducing the number of parameters, thereby improving the model's efficiency.

$$y_{i,j} = \max(x_{i \cdot s+m, j \cdot s+n})....Max Pooling$$

A neural network's dense (or fully connected) layer aggregates information from all previous layers and maps it to the output. The equation for a dense layer involves multiplying the input vector by a set of weights and adding a bias term, which determines the activation level of each neuron in the layer. The output is then typically passed

through an activation function, such as ReLU, Sigmoid, or Softmax, to introduce non-linearity and allow the model to learn complex patterns. In the context of a CNN, dense layers are typically used in the final stages of the network, where they aggregate the learned features from the convolutional and pooling layers to produce the final classification or regression output. The weights in the dense layer are learned through backpropagation during training, allowing the network to adjust and improve the mapping from input data to output predictions.

$$y_j = \sigma \left(\sum_{i=1}^{n_{in}} w_{ij} x_i + b_j \right) \dots Dense Layer$$

The softmax function is used primarily in the output layer of neural networks for multi-class classification problems. It converts the raw output scores logits into probabilities, ensuring that the sum of all predicted probabilities equals one. The softmax equation exponentiates each logit and normalizes it by dividing it by the sum of the exponentiated logits. This normalization process transforms the logits into a probability distribution, where each value represents the likelihood of a specific class. By applying softmax, the model provides a clearer interpretation of its output, enabling it to make probabilistic decisions. The class with the highest probability selected as the predicted label. Softmax is particularly advantageous in classification tasks with multiple possible categories, as it provides a coherent framework for decision-making, making it easy to identify the most probable class among many alternatives.

$$softmax(z_i) = \frac{e^{z_i}}{\sum_{j=1}^{K} e^{z_j}}$$

Recurrent neural network (RNN)

Recurrent Neural Network (RNN) produced to respond to problems from the sequences of input recognition⁵². Vanilla RNN aims to learn from input data encoded in the past but finds it hard to keep track of the information over a long period. Long Short-Term Memory (LSTM) is based on specific strategies that can catch and hold long-term associations more efficiently. Bidirectional RNNs can read input text in both forward and backward directions, allowing them to understand the contextual information from the prior and forward parts of the text at one time. In ESNs (echo state networks), the recurrent connections follow the simplest framework, whereas hierarchical RNNs with numerous layers provide an opportunity to learn complex representations from the data. Temporal resolutions divided among different neurons in Clockwork RNNs, and attention-based RNNs use mechanisms over a specific sequence segment. Every variant intended to address a challenge with various strategies combined with the ability of RNNs to perform tasks, including natural language processing, speech recognition, and time series analysis⁵³.

$$\begin{array}{llll} \textit{Hidden state update} : h_t &=& \tanh(W_hh * h_(t-1) + W_xh * x_t + b_h) \\ \textit{Output} : y &t &=& W & hy * h & t + b & y \end{array}$$

Here, *W_hh*, *W_xh*, and *W_hy* are the weight matrices for the hidden-to-hidden, input-to-hidden, and hidden-to-output connections, respectively. *b_h* and *b_y* are the hidden state and output bias terms, respectively.

Long short-term memory (LSTM)

Long short-term memory (LSTM) is a progressive version of the RNN with a structure to overcome the difficulties of long-term patterns in sequential input collection⁵⁷. LSTMs address the vanishing gradient problem that limits the capability of used RNNs to sustain information over long intervals. LSTMs include memory cells and three gating mechanisms, i.e. input, forget, and output gates, enabling the network to keep, discard, and produce information selection.

$$Forget \ gate: f_t = sigmoid(W_f * [h_(t-1), x_t] + b_f) \\ Input \ gate: i_t = sigmoid(W_i * [h_(t-1), x_t] + b_i) \\ Cell \ state \ candidate: C_tilde_t = \tanh(W_C * [h_(t-1), x_t] + b_C) \\ Update \ cell \ state: C_t = f_t * C_(t-1) + i_t * C_tilde_t \\ Output \ gate: o_t = sigmoid(W_o * [h_(t-1), x_t] + b_o) \\ Update \ hidden \ state: h \ t = o \ t * \tanh(C \ t) \\ \end{cases}$$

Here, $W_{-}f$, $W_{-}i$, $W_{-}C$, and $W_{-}o$ are the weight matrices for the forget gate, input gate, cell state candidate, and output gate. $b_{-}f$, $b_{-}i$, $b_{-}C$, and $b_{-}o$ are the corresponding bias terms. LSTMs can acquire and preserve significant contextual information over long periods, which makes them efficient at tasks that include sequences. LSTMs have demonstrated their significance in capturing complex relationships within sequential data, making them a fundamental component in various deep-learning applications⁵⁴.

Materials and methods Temporal logic of action (TLA+)

The first part of the work results concentrates on the TLA+model used to validate the safety properties for cotton disease monitoring. The TLA+specification confirms that the monitoring procedure complements safety

properties, improves results and categorizes important diseases. Exploiting a model checker to analyze the TLA + specification enabled us to assess the system's behavioural correctness across several scenarios.

Requirement elicitation of symptoms for disease monitoring

Requirement elicitation is a fundamental step in the development process, gathering and eliminating stakeholders' requirements⁵⁵. The first stage involves identifying, analyzing, and documenting the requirements for effective results. By eliciting clear, detailed information, requirement elicitation helps ensure that all project elements align with stakeholder goals. It involves techniques like interviews, surveys, observations, and making matrices to organize information effectively^{56,57}. For the cotton crop case study, requirement elicitation includes listing diseases and their symptoms in a table for disease management. Table 1 demonstrates the Requirement Elicitation of Observed Symptoms. The elicitation helps stakeholders, such as farmers and researchers, understand the conditions and symptoms that need an efficient solution design and approach.

Requirement verification using temporal logic of action (TLA+)

The verification method confirmed that the safety properties specified in the TLA+model have been ensured effectively. The platform corrects transitions between states, ensuring that a suitable response (such as generating an alert) activates disease detection. Moreover, formal verification guarantees no chance of incorrect identification within the defined safety restrictions.

```
---- MODULE CottonDiseasePrediction ----
EXTENDS Integers, Sequences, TLC, FiniteSets
CONSTANTS SymptomInputs, SymptomsByDisease, DiseaseNames
(* PlusCal algorithm for disease identification *)
    (* --algorithm CottonDiseasePrediction
variables DiseaseMatches = [d ∈ 1..Len(DiseaseNames) |→ 0],
    MostLikelyDisease = "",
    HighestMatchCount = 0,
    i = 1,
    diseaseSymptoms,
    newMatchCount;
```

The CottonDiseasePrediction module, created through PlusCal, aims to forecast cotton plant diseases based on user-provided symptoms. The model incorporates constants such as SymptomInputs, denoting the symptoms exhibited by a cotton plant; SymptomsByDisease, which associates each disease with its respective symptoms; and DiseaseNames, which contains a list of possible diseases. The disease identification mechanism evaluates the user's reported symptoms against the recorded symptoms of each condition to determine the most accurate match.

```
begin

CountMatches:

while i \le Len(DiseaseNames) do

(*Local variable assignments*)

diseaseSymptoms = SymptomsByDisease[i];

newMatchCount = Cardinality(diseaseSymptoms \cap SymptomInputs);

DiseaseMatches[i] = newMatchCount;

i = i + 1;

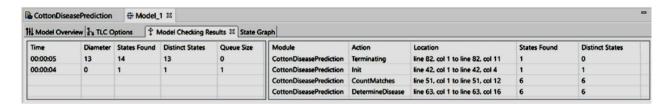
end while;
```

The algorithm starts establishing several factors, including DiseaseMatches (an array to monitor the match count for each disease), MostLikelyDisease (to retain the disease with the highest match), and HighestMatchCount (to record the maximum number of matching symptoms). During the CountMatches phase, the algorithm examines each disease, calculates the intersection between user-provided symptoms and established symptoms, and tallies the matches—the match count for each disease recorded in the DiseaseMatches array. Upon completion of all match calculations, the algorithm re-initializes the loop variable to determine which disease displays the highest match.

Requirement ID	Disease name	Yellow leaves	Leaf spots	Sticky residue	Curling leaves	Stunted growth	Discolored leaves	Fuzzy growth	Target- shaped spots	Powdery deposits	Wilting
Req_1	Aphids	1	1	1	1	X	X	x	x	x	X
Req_2	Army worm	x	1	X	x	1	1	x	X	x	X
Req_3	Bacterial blight	1	X	X	x	1	1	X	x	x	1
Req_4	Powdery mildew	x	1	X	1	X	X	1	X	1	X
Req_5	Target spot	X	1	X	1	1	1	x	1	x	X

Table 1. Requirement elicitation of observed symptoms.

Fig. 3. Temporal state of action for disease symptoms.



Module	Action	Location	States Found	Distinct States
CottonDiseasePrediction	CountMatches	line 51, col 1 to line 51, col 12	6	6
CottonDiseasePrediction	DetermineDisease	line 63, col 1 to line 63, col 16	6	6
CottonDiseasePrediction	Init	line 42, col 1 to line 42, col 4	1	1
CottonDiseasePrediction	Terminating	line 82, col 1 to line 82, col 11	1	0

Fig. 4. Model checking results for module cotton disease.

```
(* Reset the counter for the next loop*)

i := 1;

DetermineDisease:

while i ≤ Len(DiseaseNames) do

if DiseaseMatches[i] > HighestMatchCount then

MostLikelyDisease := DiseaseNames[i];

HighestMatchCount := DiseaseMatches[i];

end if;

i := i + 1;

end while;

print(<<"Most likely disease based on symptoms is: ", MostLikelyDisease,

" with ", HighestMatchCount, " matching symptoms.">>>);

end algorithm*)
```

During the DetermineDisease phase, the algorithm evaluates the match counts for all diseases to identify the most corresponding symptoms. Should a disease exhibit a higher match count than the highest, the algorithm adjusts MostLikelyDisease and HighestMatchCount, respectively. The disease with the highest probability and its corresponding match count are displayed, indicating the condition that most accurately aligns with the given symptoms.

Invariants and model checking

The invariants InvariantNonNegativeMatches and InvariantMatchLimit ensure that the matching process remains logically sound. InvariantNonNegativeMatches guarantees that the match count for any disease (DiseaseMatches[j]) is never negative. InvariantMatchLimit ensures that the match count not exceed the total number of input symptoms (Cardinality(SymptomInputs)), maintaining realistic bounds on the comparisons. Figure 3 represents the Temporal State of Action for Disease Symptoms, and Fig. 4 shows the State Space Actions of Module Cotton Disease.

```
InvariantNonNegativeMatches \triangleq \forall j \in 1..Len(DiseaseNames) : DiseaseMatches[j] \geqslant 0 \\ InvariantMatchLimit \triangleq \forall j \in 1..Len(DiseaseNames) : DiseaseMatches[j] \leqslant Cardinality(SymptomInputs) \\ Next \triangleq CountMatches \lor DetermineDisease \lor Terminating
```

Safety property for requirement correctness

The Safety property ensures that the match count for any disease (*DiseaseMatches[j]*) never exceeds the current highest match count (*HighestMatchCount*), maintaining consistency during the disease identification process.

```
Safety \triangleq \forall j \in 1..Len(DiseaseNames) : DiseaseMatches[j] \leqslant HighestMatchCount
```

Deep learning models

Experimental setup and deployment

This work used an input image size of 256×256 for CNN models to ensure enough detail was captured from the cotton leaf images while keeping computation manageable. However, models like VGG19 and MobileNet are pretrained on the ImageNet dataset, which uses a default input size of 224×224 , so their architectures are optimized for that size—hence, resizing input images accordingly when using these models is important. A batch size of 32 was consistently used across models as it balances training speed and GPU memory usage well. On GPUs, batch size doesn't usually cause problems as long as it fits in memory, and keeping it consistent helps ensure stable and comparable training performance across models.

Dataset description

The dataset includes images for six common cotton leaf diseases—Aphids, Army Worm, Bacterial Blight, Powdery Mildew, and Target Spot—and healthy leaves for comparison. The dataset includes 3601 images. It is specifically designed to focus on diseases affecting only the leaves, without reference images for stems, buds, flowers, or bolls. The targeted approach makes it ideal for training machine learning models to identify diseases, helping in detection practices for cotton crops. Figure 5 shows the dataset sample images for cotton crop dataset.

Deep learning model details

The convolutional neural network (CNN) model used for monitoring and predicting cotton leaf diseases follows a layered architecture designed to extract and classify image features effectively. The input layer receives a batch of 32 RGB images, each with a size of 256×256 pixels. The model starts with convolutional layers (Conv2D) with 3×3 kernels and ReLU activation, progressively increasing the number of filters from 32 to 64 to capture intricate features. MaxPooling2D layers follow each convolutional layer, reducing the spatial dimensions by half, thus downsampling the images. This sequential pattern of convolution and pooling continues for five layers, with the feature maps shrinking in size while retaining the most significant information. After flattening the pooled feature maps into a 1D vector, a dense layer with 64 neurons and ReLU activation is applied, followed by the output layer uses softmax activation to classify the input into one of the six disease categories. Table 2 shows deep learning model details.

Justify hyperparameter choices

The choice of hyperparameters in this CNN model for cotton leaf disease classification is critical for ensuring both model performance and stability. The learning rate is set to the default value of 0.001, providing a balanced training approach and ensuring the model converges smoothly without overshooting the minima. The architecture comprises 5 convolutional layers (Conv) and 5 pooling layers (Pool), which allow the network to learn complex hierarchical patterns from the input data. The 3×3 filter size is chosen as it is standard for CNNs, offering a good trade-off between capturing spatial features and reducing the number of parameters, thus minimizing computational costs. The number of filters increases from 32 to 64 as the network deepens, enabling richer feature extraction while maintaining a manageable model size. ReLU activation is used in the convolutional layers to mitigate the vanishing gradient problem, while Softmax is employed in the output layer to handle multi-class classification. A batch size of 32 is selected to balance GPU memory usage and the stability

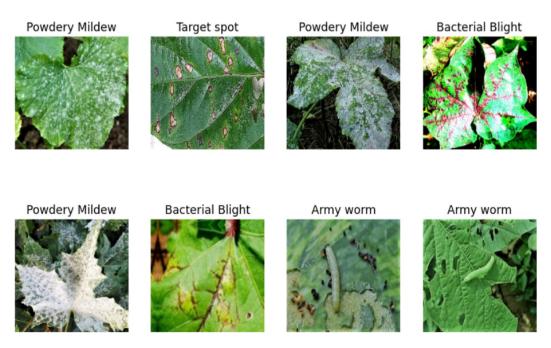


Fig. 5. Shows the dataset sample images.

Layer type	Output shape	Details
Input layer	(32, 256, 256, 3)	The batch of 32 RGB images, size 256×256
Conv2D	(32, 254, 254, 32)	32 filters, 3×3 kernel, ReLU activation
MaxPooling2D	(32, 127, 127, 32)	2×2 pool size, downsampling
Conv2D	(32, 125, 125, 64)	64 filters, 3×3 kernel, ReLU activation
MaxPooling2D	(32, 62, 62, 64)	2×2 pool size
Conv2D	(32, 60, 60, 64)	64 filters, 3×3 kernel, ReLU activation
MaxPooling2D	(32, 30, 30, 64)	2×2 pool size
Conv2D	(32, 28, 28, 64)	64 filters, 3×3 kernel, ReLU activation
MaxPooling2D	(32, 14, 14, 64)	2×2 pool size
Conv2D	(32, 12, 12, 64)	64 filters, 3×3 kernel, ReLU activation
MaxPooling2D	(32, 6, 6, 64)	2×2 pool size
Flatten	(32, 2304)	Converts feature maps to 1D vector
Dense	(32, 64)	Fully connected layer, 64 neurons, ReLU activation
Output Dense	(32, 6)	6 neurons for 6 classes, softmax activation

Table 2. Deep learning model details.

Hyperparameter	Value	Justification				
Learning rate	Default / 0.001 (assumed)	A moderate learning rate ensures stable convergence without overshooting minima				
Number of Conv layers	5 Conv + 5 Pool	Deeper architecture enables learning complex features; each Conv-Pool pair extracts hierarchical patterns				
Filter sizes	3×3	Standard kernel size for spatial locality while reducing parameters compared to larger kernels				
Number of filters	32 → 64	Increasing depth allows richer feature extraction while keeping the model size manageable				
Activation function	ReLU (in Conv), Softmax (in Output)	ReLU avoids vanishing gradients; Softmax is ideal for multi-class classification				
Batch size	32	A common choice balancing GPU memory use and training stability				
Optimizer	Assumed Adam	Adaptive learning rates make it suitable for most CNN-based classification tasks				

Table 3. Hyperparameter choices justification.

of the training process. The Adam optimizer, known for its adaptive learning rates, is assumed to be used, which is well-suited for most CNN-based tasks. Table 3 shows hyperparameter choices justification.

Hyperparameters chosen based on extensive experimentation: a learning rate of 0.001 ensures stable convergence, dropout rates of 0.3 and 0.5 prevent overfitting, and filter sizes 3×3 maintain spatial hierarchy. CottonLeafNet was selected for its accuracy and computational efficiency balance, outperforming heavier models in resource-limited agricultural settings.

This work uses TensorFlow and Keras libraries for model construction, using the functionalities provided by these libraries to handle data processing and augment training data effectively 58,59 . The network begins with a convolutional layer with 32 filters and several layers with increased filter sizes. Each convolutional layer uses a (3×3) kernel and ReLU activation to ensure the model learns non-linear patterns 60 . Max-pooling layers are combined after each convolutional layer to reduce the spatial dimensions, which helps decrease computation and prevents overfitting by extracting dominant features.

Following the convolutional and pooling layers, the model flattens the extracted feature maps into a onedimensional vector, passing through a fully connected (dense) layer with 64 neurons. This dense layer further refines the learned features before the final output layer. The output layer contains six neurons, each representing a class in the cotton crop classification problem, and uses a softmax activation function. This setup assigns probabilities to each class, enabling the model to output the likelihood that an image belongs to a specific category.

Figure 6 represents the architecture of a CNN used for image classification tasks. It starts with an input layer, passing images into the network. The ConvLayer applies convolution operations using filters (e.g., 3×3), creating feature maps. These are normalized with BatchNormalization and activated using ReLU to introduce non-linearity. MaxPooling reduces the spatial dimensions while retaining essential features. The convolution, normalization, and pooling processes are repeated to deepen the network. Flattening converts feature maps into a vector passed through FullyConnectedLayers for dense feature extraction. Dropout prevents overfitting, and the OutputLayer uses softmax for final class probabilities.

Experiments with 100, 150, 300 epochs and analysis results

Figure 7 illustrates performance comparisons across epochs. The CNN model trained for 50, 100, and 300 epochs to assess the effect of training duration on model performance. At 50 epochs, the model achieved an accuracy of 94.53%, with a precision of 94.31%, recall of 95.04%, and F1 score of 94.46%. Training for 100 epochs improved the accuracy to 96.61%, and further training for 300 epochs yielded the best performance with an accuracy of 98.7%, precision of 98.63%, recall of 98.7%, and F1 score of 98.65%. These results demonstrate that increasing

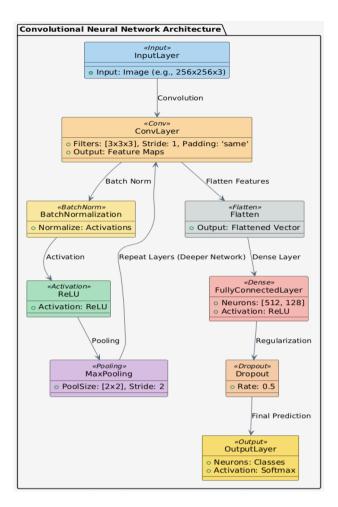


Fig. 6. CNN architecture.

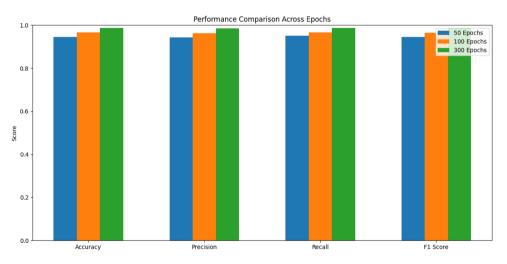


Fig. 7. Performance comparison over epochs.

the number of epochs can significantly enhance the model's ability to learn and generalize, provided overfitting is controlled.

RNN such as LSTM as a comparison and report findings

When comparing the performance of the CNN and LSTM models, it is evident that the CNN significantly outperformed the LSTM in classifying cotton leaf diseases. The CNN model achieved an overall accuracy of

98.7%, with F1-scores across all classes (e.g., 0.90 for Powdery Mildew and 0.87 for Army Worm), indicating reliable and consistent predictions. In contrast, the LSTM model only reached an accuracy of 48%, with lower precision and recall scores across most classes, particularly struggling with classes like Target Spot and Bacterial Blight. This suggests that CNN, better suited for image data due to its ability to capture spatial features, is more effective and stable than LSTM for this classification task.

Ablation studies to analyze the impact of data augmentation and hyperparameters

The ablation study reveals that data augmentation significantly improves model performance, as removing it led to a drop in accuracy. Interestingly, eliminating image rescaling resulted in the highest test accuracy, suggesting that the rescaling process might have negatively affected input quality. Changes in hyperparameters such as optimizer, kernel size, and the number of filters had little to no impact on accuracy. Figure 8 shows Ablation study Impact of Preprocessing and hyperameters. The study highlights that data preprocessing techniques, particularly augmentation and rescaling, play a more critical role in model performance than minor architectural changes.

Computational efficiency and real-world applicability

Running the model on a GPU significantly accelerated training and evaluation, enabling efficient experimentation with different configurations and ablation studies. Computationally, this demonstrates the practicality of deploying deep learning models in real-time scenarios where speed is crucial, such as in mobile or IoT-based plant disease detection systems. In real-world applications, the model's ability to identify cotton diseases can assist farmers in making timely decisions, reducing crop loss, and improving yield. The study also highlights how tuning data preprocessing and architecture can enhance model reliability, making it suitable for deployment in agricultural monitoring tools. By using a deep learning model, the network learns hierarchical features that enable it to differentiate between understated differences in plant diseases and pests. Figure 9 demonstrates the sample prediction of cotton crop diseases. The CNN model is used in this study to analyze visual features such as colour variations, texture anomalies, and irregularities in leaf structures. These competence features of CNNs in agricultural disease detection provide a solution for detection. Such models can help farmers take preventive measures to improve crop health and yield. These predictions also demonstrate the probability of further scalability across various plant species and environmental conditions.

Discussion and results Disease monitoring model acceptance criteria

The Disease Monitoring Model is constructed on well-defined requirements and formal verification to ensure its reliability and correctness in monitoring cotton crop disease. Our previous work in confirming the correctness properties of *safety* for autonomous robotic multi-agent systems^{61–63} and flood monitoring systems^{64–68} have helped us in the formal modeling and verification of cotton crop disease detection. Formal modeling constructs the model behaviour in identifying diseases based on input symptoms. The model ensures correctness and reliability throughout construction by formal requirements into functional and non-functional categories.

Functional requirements, which are written in the table, define the critical tasks of the model, such as initializing key variables, iterating through diseases, calculating symptom matches, and identifying the most likely disease. Table 4 presents the acceptable criteria for the disease detection model. The associated acceptance criteria confirm that the implementation follows these defined behaviors. For example, DiseaseMatches and MostLikelyDisease are initialized appropriately, while iterations through DiseaseNames ensure accurate match calculations and disease identification.

Non-functional requirements and efficient handling of various disease symptoms ensure that the model performance remains robust even when processing multiple diseases and symptoms. Input and output

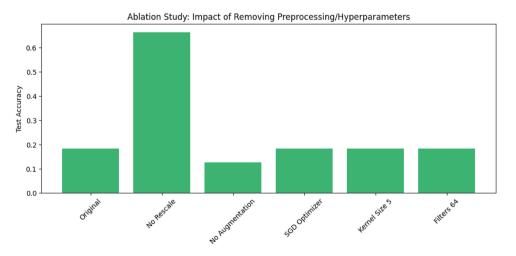


Fig. 8. Ablation study impact of preprocessing and hyperameters.



Fig. 9. Sample of cotton disease predictions.

requirements validate that the input symptom set and disease list are well-formed, while output specifications confirm that the system provides clear, actionable information regarding identified diseases and matching symptom counts.

Formal verification plays a critical role in validating the model requirements. Probable errors, such as failing to identify diseases with zero matches, are addressed by confirming logical reliability and correctness. The structured acceptance criteria are a benchmark, ensuring the model meets stakeholders' prospects while maintaining scalability, reliability, correctness, and clarity in disease identification.

Performance evaluation of deep learning model

Why accuracy varies across diseases

Accuracy varies across cotton leaf disease classes due to multiple interrelated factors. As the Table 5 Classification report the visual similarity between diseases, such as Bacterial Blight and Target Spot, often leads to model confusion due to overlapping symptoms, whereas distinctly manifested diseases like Powdery Mildew—characterized by white powdery lesions—yield higher precision (0.98). Minor class imbalances and differences in image quality or intra-class variability also impact performance; for instance, Bacterial Blight

Requirement ID	Requirement type	Description	Acceptance criteria
Req_1	Functional	The algorithm must initialize variables to track disease matches and expected diagnoses.	Variables <i>DiseaseMatches</i> , <i>MostLikelyDisease</i> , and <i>HighestMatchCount</i> are initialized to 0 or empty.
Req_2	Functional	The algorithm must iterate through all diseases to count symptom matches	The CountMatches loop iterates over DiseaseNames, updating DiseaseMatches with the count of matches.
Req_3	Functional	The algorithm should calculate the number of matching symptoms for each disease	newMatchCount correctly reflects the intersection of disease symptoms and SymptomInputs.
Req_4	Functional	The algorithm should update <i>MostLikelyDisease</i> to the disease with the highest match count.	MostLikelyDisease is assigned to the disease with the greatest DiseaseMatches count in the DetermineDisease loop.
Req_5	Functional	The algorithm must print the most expected disease and the number of matching symptoms.	Output statement displays MostLikelyDisease and HighestMatchCount.
Req_6	Non-functional	The algorithm should efficiently handle a large number of diseases and symptoms.	Completion time is within acceptable bounds when the number of <i>DiseaseNames</i> and <i>SymptomsByDisease</i> is large.
Req_7	Input	The input set SymptomInputs requirement contains the symptoms observed in the cotton plant.	SymptomInputs is a valid set with elements that can be compared to symptoms in SymptomsByDisease.
Req_8	Input	DiseaseNames should contain a list of all potential diseases	DiseaseNames is a non-empty sequence matching the order of SymptomsByDisease.
Req_9	Output	The output should include the identified disease and matching symptom count.	The output string includes the names Most LikelyDisease and HighestMatchCount.
Req_10	Error handling	If no disease has any matching symptoms, $MostLikelyDisease$ should remain an empty string.	MostLikelyDisease is empty if the HighestMatchCount is 0.

Table 4. Acceptance criteria of disease detection model.

Class	Precision	Recall	F1-score	Accuracy	Support
Aphids	0.75	0.89	0.81	0.89	61
Army worm	0.90	0.84	0.87	0.84	62
Bacterial Blight	0.62	0.73	0.67	0.73	66
Healthy	0.79	0.73	0.76	0.73	56
Powdery Mildew	0.98	0.83	0.90	0.83	52
Target spot	0.81	0.71	0.76	0.71	55

Table 5. Classification report.

showed lower precision (0.62), possibly due to noisy or blurred samples. In some cases, recall and precision trade-offs indicate class-specific misclassification tendencies: Aphids had high recall (0.89) but lower precision (0.75), suggesting over-prediction, while Army Worm demonstrated substantial precision (0.90) but moderate recall (0.84), implying under-detection. Additionally, overlapping symptoms among diseases and healthy leaves (e.g., discolouration, necrotic spots) contribute to inter-class confusion, affecting recall and precision. Finally, the diversity of test samples, including variations in lighting or leaf maturity, particularly in the Healthy class, influences the model's ability to generalize, underscoring the need for high-quality, diverse datasets.

Confusion matrix

The provided confusion matrix illustrates the performance of a deep learning model for predicting cotton leaf diseases. The matrix classifies five categories: Aphids, Army Worm, Bacterial Blight, Healthy, Powdery Mildew, and Target Spot. Each row represents the actual class, while the columns correspond to the predicted classes. High values along the diagonal indicate correct predictions, with Bacterial Blight (66) and Target spot (47) having the highest accuracy in classification. Misclassifications are apparent in non-diagonal cells, such as the 7 misclassified Armyworms predicted as Aphids and the 6 misclassified Powdery Mildew predicted as Aphids. Figure 10 presents confusion matrix for cotton crop diseases leaf and healthy leaf The model performs well overall, as evidenced by the significant concentration of correct classifications, but there is still room for improvement in differentiating specific disease categories.

ROC curve

The ROC curve for the multi-class classification model demonstrates its effectiveness in predicting cotton leaf diseases. Each class, including Aphids, Armyworm, Bacterial Blight, Healthy, Powdery Mildew, and Target Spot, represents a distinct line with corresponding AUC (Area Under the Curve) values. The model shows strong classification performance, with most classes achieving AUC values above 0.96, indicating high predictive accuracy. The highest AUC values are observed for Aphids, Armyworms, and Healthy and Powdery Mildew (AUC = 0.98), reflecting their well-separated distributions regarding true and false positive rates. Bacterial Blight shows a slightly lower AUC value of 0.96, suggesting a marginal decrease in classification performance for this category. Figure 11 shows ROC Curve for multiple classes of cotton diseases The Chance line (dashed) represents

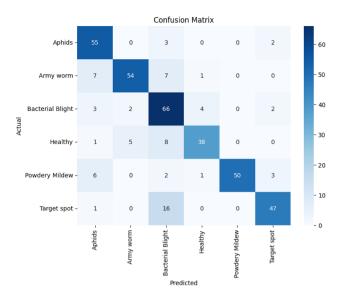


Fig. 10. Confusion matrix for cotton crop diseases leaf and healthy leaf.

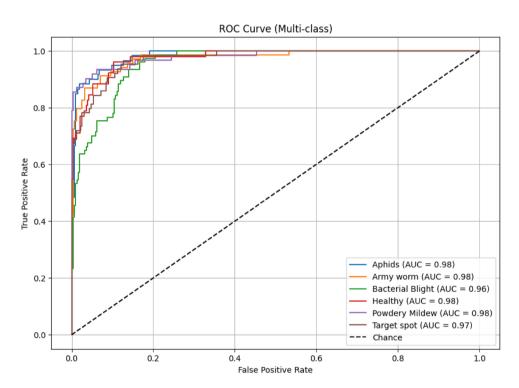


Fig. 11. ROC curve for multiple classes of cotton diseases.

random guessing, further shows the model's superior performance across the categories. Overall, the ROC curve illustrates a robust classification ability, with minimal misclassification across the cotton leaf disease categories.

Confidence intervals (95%)

The 95% confidence interval for accuracy, ranging from 0.286 to 0.380, indicates that with 95% confidence, the true accuracy of the model falls within this range. This means that if you repeatedly test the model on different datasets or under slightly varying conditions, 95% of the time, the accuracy would fall between 28.6% and 38.0%. The relatively wide range suggests considerable uncertainty in the model's performance, possibly due to factors such as high variability in the data or insufficient model training. While the model's accuracy may still be helpful, this range highlights the importance of gathering more data or refining the model to increase the precision and reliability of the performance estimate.

Author and year	Method used	Dataset source	Accuracy (%)	Identified gaps	Contribution
Pandey et al. (2023) ¹³	Deep Convolutional Neural Network (CNN)	2293 images of diseased leaves	97.98	Model verification lacking	High accuracy in disease detection with deep CNN
Rai & Pahuja (2023) ¹⁴	Improved Deep CNN	Cotton leaf images	97.98	Model deployment issues	Achieved high accuracy in leaf disease classification
Senthil Pandi et al. (2024) ¹⁸	Inception-V3 Transfer Learning (ITL-CHB)	Black Gram disease dataset	98	Data imbalance in training	Improved disease classification accuracy using transfer learning
Stephen et al. (2024) ¹⁹	Deep Learning (CNN)	Big data-based cotton monitoring system	93.9	Rare disease detection issues	Big data-driven system for improved plant health monitoring
Arathi & Dulhare (2023) ²⁰	DenseNet-121 with Transfer Learning	Cotton leaf disease dataset	91	Requires fine-tuning for rare diseases	Enhanced cotton disease classification with transfer learning
Vibhute & Kale (2023) ²¹	Machine Learning (PLSR, SVM, SAM)	Soil data (spectroradiometer, satellite images)	95	Limited generalizability to other crops	Machine learning models for soil management in cotton farming
Paul et al. (2024) ²⁵	YOLOv8 for Object Detection	Capsicum harvesting dataset	96.7	Requires extensive training data	Automated harvesting with YOLOv8 for detection and real-time application
Proposed method (ours)	MobileNet, VGG19,CNN, LSTM, RNN, TLA+	Hybrid (public+field data)	98.7	Addressed requirments correctness & model deployment	Mathematical verification of requirements, multiple class cotton disease prediction

Table 6. Comparison with previous studies.

K-fold cross-validation (k = 10) for generalization

To ensure robust generalization of the proposed model, a 10-fold cross-validation conducted. Several enhancement techniques incorporated into the model architecture and training process. Firstly, data augmentation strategies such as random flips, rotations, and zooming were employed to artificially expand dataset diversity, reducing the risk of overfitting and enhancing the model's ability to generalize to unseen data. Batch normalization was applied after each convolutional layer to stabilize learning by normalizing activations, improving training dynamics and model robustness. Additionally, dropout was introduced in the dense layer before the output to mitigate overfitting by randomly disabling neurons during training, forcing the network to learn more generalized features. L2 regularization further discouraged large weight magnitudes, promoting simpler, more generalizable models. The training was also optimized using early stopping, which halted learning when validation loss ceased to improve, and a learning rate scheduler (ReduceLROnPlateau) dynamically reduced the learning rate upon stagnation in validation performance. The k-fold validation results demonstrated encouraging performance, with the best validation accuracy reaching 82.64% (Fold 5) and an average accuracy of 80.56% across all folds. The accuracy range (0.7603–0.8264) indicated consistent performance with low variance, suggesting that the model reliably captures the distinguishing features of cotton leaf diseases and generalizes well across different data partitions.

Compare performance with state-of-the-art models (VGG19, Alex-Net, Mobile-Net, Efficient-Net)

This study conducted a comparative analysis of the baseline CNN achieved a commendable performance with an accuracy of 95.57% and a precision, recall, and F1-score of 0.96, indicating reliable but suboptimal classification capability. In contrast, MobileNet demonstrated superior performance, attaining 99.74% accuracy with perfect scores (1.00) across all key metrics, including precision, recall, and F1-score. Although VGG19 initially yielded moderate results, post-fine-tuning, its performance significantly improved and aligned with MobileNet's, reaching 99.74% accuracy and perfect evaluation metrics. Despite the comparable accuracy, MobileNet's lightweight architecture offers efficiency, particularly for resource-constrained or mobile environments, making it preferable for real-time field deployment. Table 6 shows comparison with previous studies. These findings underscore the effectiveness of transfer learning and highlight that, when fine-tuned appropriately, pre-trained models like MobileNet and VGG19 can significantly outperform conventional CNNs in classification accuracy and generalization ability.

Conclusion

This work focuses on the significance of formal modeling and formal verification for improving the reliability and correctness of cotton crop disease monitoring and detection methods. Using the TLA + improved a robust mathematical model that systematically verified the requirements for disease symptom detection. Using model checking, we ensured the constructed model's correctness, centered on validating safety properties. The safety property verified to confirm the method's ability to match disease symptoms with the highest confidence correctly. This approach guarantees a consistent and reliable framework for disease monitoring. Moreover, deep learning models, i.e. CNN, LSTM, and RNN demonstrated the effectiveness of deep learning in predicting cotton crop diseases. The CNN model achieved an overall accuracy of 98.7%, with class-specific accuracy metrics ranging from with F1-scores across all classes (e.g., 0.90 for Powdery Mildew and 0.87 for Army Worm).

Contributions

I. Formal verification of disease symptoms using TLA+: This Work presents TLA+ as a formal approach for verifying requirements in agricultural disease detection. The application of formal verification ensures the robustness of the monitoring framework. We showed model checking using TLA+ to verify critical symp-

- tom detection parameters, thereby increasing confidence in the accuracy of disease detection under various crop conditions.
- II. Formal methods enhanced reliability and correctness: This Work is set apart using formal verification, resulting in a reliable and scalable framework for crop monitoring. This method rectifies a critical shortcoming in the agricultural industry by ensuring correctness in symptom requirements detection when applying formal Modeling and verification to crop management methods.
- III. Deep learning model for disease prediction: The CNN, LSTM, RNN model is trained to predict six situations, including Aphids, Armyworms, Bacterial Blight, Powdery Mildew, Target Spot, and Healthy crop states.
- IV. Prospective for field deployment and practical impact: This approach corresponds with actual agricultural needs, providing a practical choice for evaluating cotton crop health. The framework's robust predictive accuracy and reliability indicate significant potential for agricultural use, improving disease management procedures and resulting in more crop yields.

Future work Short-term objectives

In the short term, the aim is to ensure the effective performance of the disease detection framework for cotton crops. Deep learning model to identify specific diseases, like Aphids, Armyworms, Bacterial Blight, Powdery Mildew, and Target Spot, while recognizing healthy crop conditions. Furthermore, we use TLA+to verify an understanding of each disease's symptoms, utilizing model checking to validate the correctness of symptom detection. Collaborating with agricultural professionals during requirement collection to improve and ensure it matches users' requirements in agrarian environments.

Long term objectives

In the long term, we propose to increase the impact of our cotton crop monitoring system by broadening its applicability to other vital crops, including rice, wheat, and corn, and to determine diseases affecting crops by training it on novel, crop-specific disease datasets. The proposed approach provides a structure applicable to various crops it is used for a broader spectrum of farmers and agricultural sectors, improving its reliability across various farming communities. A monitoring approach aims to transform conventional agrarian methods, enhancing both productivity and environmental conservation in the long term. The strategy coincides with global objectives for sustainable agriculture and food security through robust crop management practices.

Data availability

The dataset analysed during the current study is available in the "Cotton Plant Disease" dataset, https://www.kag gle.com/datasets/dhamur/cotton-plant-disease/dataAll coding files, including deep learning models and TLA+ toolbox modules, are publicly available on GitHub at https://github.com/abdulpk/MuhammadMusa for further use and analysis.

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Author contributions

Abdul Rehman: Conceptualized the study, developed the TLA+ formal models, and performed model verification for disease symptom requirements and reviewed, and implemented deep learning models CNN, LSTM, RNN for disease prediction.Dr. Nadeem Akhtar: Designed and implemented the deep learning framework, including CNN model training and evaluation for disease prediction and formal verification of correctness properties for this work.Dr. Omar H Alhazmi: Conducted data collection, preprocessing, and analysis of results, and contributed to manuscript writing and revisions.

Declarations

Competing interests

The authors declare no competing interests.

Additional information

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