



Author Correction: Molecular control via dynamic bonding enables material responsiveness in additively manufactured metallo-polyelectrolytes

Correction to: *Nature Communications*
<https://doi.org/10.1038/s41467-024-50860-6>,
 published online 10 August 2024

<https://doi.org/10.1038/s41467-024-52457-5>

Published online: 16 September 2024



Seola Lee , Pierre J. Walker , Seneca J. Velling , Amylynn Chen,
 Zane W. Taylor , Cyrus J.B.M Fiori , Vatsa Gandhi , Zhen-Gang Wang &
 Julia R. Greer

In the Acknowledgements section, the following sentence, ‘The authors gratefully acknowledge the financial support from the Center for Autonomous Systems and Technologies (CAST) at Caltech, the Institute for Collaborative Biotechnologies from the Army Research Office (ARO), and the Schwartz/Reisman Collaborative Science Program from the Schwartz/Reisman Foundation’ should have read, ‘The authors gratefully acknowledge the financial support from the Center for Autonomous Systems and Technologies (CAST) at Caltech and the Schwartz/Reisman Collaborative Science Program from the Schwartz/Reisman Foundation. Research was also sponsored, in part, by the U.S. Army Research Office and accomplished under contract W911NF-19-D-0001 for the Institute for Collaborative Biotechnologies’. The original article has been corrected.

Open Access This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article’s Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article’s Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

© The Author(s) 2024