



## OPEN Parameter optimization of key components in seed-metering device for pre-cut seed stems of *Pennisetum hybridum*

Chong Liu<sup>1,2</sup>, Xiongfei Chen<sup>1,2</sup>, Qiang Xiong<sup>1,2</sup>, Muhua Liu<sup>1,2</sup>, Junan Liu<sup>1,2</sup>✉, Jiajia Yu<sup>1,2</sup>, Peng Fang<sup>1,2</sup>, Yihan Zhou<sup>1,2</sup>, Chuanhong Zhan<sup>1</sup> & Yao Xiao<sup>1</sup>

To address the issues of missed seeding and seed stem jamming—factors that contribute to unstable performance in *Pennisetum hybridum* planting device, this study optimize the key components of the pre-cut stem planting device and evaluated its operational performance, thereby improving planting quality. Based on the results of preliminary experiments and discrete element method (DEM) simulation analysis, the critical components of the seed-metering device and their key influencing parameters were identified. Single-factor experiments were conducted to determine the appropriate parameter range. These were followed by a quadratic regression orthogonal rotation combination design for parameter optimization and the development of a response model for influencing factors. Finally, validation tests were performed to assess the effectiveness of the optimized parameters. The parameter optimization revealed that the optimal working parameter combination for the seed-metering device was: seed-cleaning rubber roller rotation speed (A) at 62.2 r/min, seed-filling rubber roller rotation speed (B) at 23 r/min, and conveyor belt operating speed (C) at 0.045 m/s. Under these conditions, the theoretically qualified seeding rate ( $Y_1$ ) reached 92.5%, the missed seeding rate ( $Y_2$ ) was 2.13%, and the reseeding rate ( $Y_3$ ) was 5.37%. Validation experiment confirmed that  $Y_1 = 91.8\%$ ,  $Y_2 = 2.5\%$ ,  $Y_3 = 5.7\%$ , with a relative error of 0.76%. The single-factor experimental results indicated that as A and B increased,  $Y_1$  initially rose and then declined; as C increased,  $Y_1$  gradually decreased. The interaction factor analysis of the orthogonal experimental results showed that the order of influence on seeding quality was:  $A > B > C$ . The verification tests confirmed the reliability of the optimized parameter scheme, providing both theoretical basis and technical support for improving the operational performance of the *Pennisetum hybridum* seed-metering equipment.

**Keywords** Mechanized planting, Ordered seed conveying, Parameter optimization, *Pennisetum hybridum*, Pre-cut seed stem

*Pennisetum hybridum* (*Pennisetum sinense* Roxb)<sup>1</sup> is a high-quality forage grass known for its high survival rate, high biomass yield, and strong drought resistance. In addition to its agricultural value, it plays an important ecological role in combating desertification and conserving soil and water resources<sup>2–4</sup>. However, due to the naturally low germination rate of *P. hybridum* seeds, farmers typically adopt the planting method involving the pre-cutting and planting of seed stems. This manual approach is inefficient, labor-intensive, and presents a major bottleneck to large-scale planting and industrialization. Therefore, developing a seed-metering device tailored to the physical characteristics of pre-cut *P. hybridum* seed stems is of both economic and ecological significance. Such device would improve planting efficiency, reduce labor costs and expand the application of this species in desert greening.

At present, the research on seed stem crop seeding machinery is mainly focused on the pre-cut seed stem seed-metering device, and some scholars have optimized the structure of these devices. For example, KAMAL KISAN, an Indian research institution, has developed a roller-type automatic seed-metering device that adopts alternating 20° inclined clamp plates to align seed stems, improving the qualified seed-metering rate by 9.66% compared with the original design. However, it is only suitable for small pre-cut seed stems; larger seed stems cannot be accommodated due to the limited size of seed metering groove, which easily leads to blockages in seed

<sup>1</sup>College of Engineering, Jiangxi Agricultural University, Nanchang 330045, China. <sup>2</sup>Jiangxi Provincial Key Laboratory of Modern Agricultural Equipment, Nanchang 330045, China. ✉email: liu\_jun\_an@jxau.edu.cn

conveying pipelines<sup>5</sup>; Zheng Shuhe et al. designed a roller-type seed-stem metering device with an optimized seed groove structure using elastic padding materials, which enhanced the smoothness and stability of seed metering and increased the qualified metering rate to 93.33%<sup>6</sup>; Chen Lintao et al. developed a pre-cut seed-metering device featuring a friction-band precision seed-metering mechanism that showed excellent adaptability to various pre-cut seed-stem varieties, achieving the seed filling qualification index of 94.13%<sup>7</sup>; Naik et al. designed a conveyor-belt-based pre-cut automatic seed-metering device. However, the first-stage belt conveyor exhibited relatively large seed delivery errors, with a qualification rate of only 88%, and the seed protection plate frequently collided with seed stems, causing axillary buds loss<sup>8</sup>; Scholars such as Ale and Biao Zhang et al.<sup>9–11</sup> have conducted relevant research and improvements on seed-metering devices, for instance, by adding gravity-based seed cleaning mechanisms or improving the structure of the clamping plate to enhance seed-metering performance, yet issues like seed under-filling persist. Some scholars have also improved the seeding performance by integrating additional functions into the seed-metering device. For example, Gan Fangfang et al.<sup>12</sup> designed a pre-cut seed stem compensator Device for cassava planting machinery, could solve the problem that the qualified rate was not high enough and the process of filling and clearing seeds was discontinuous; Li Shangping et al. designed a roller-rake type seed-metering mechanism that removes excess seed stems using a pressure plate and incorporates a self-regulating control system to manage metering pressure and flow, achieving uniform seed distribution<sup>13</sup>. Other researchers have also conducted extensive studies on efficient seed-metering technologies for seed stem crops<sup>14–19</sup>, but most remain at the technical development stage.

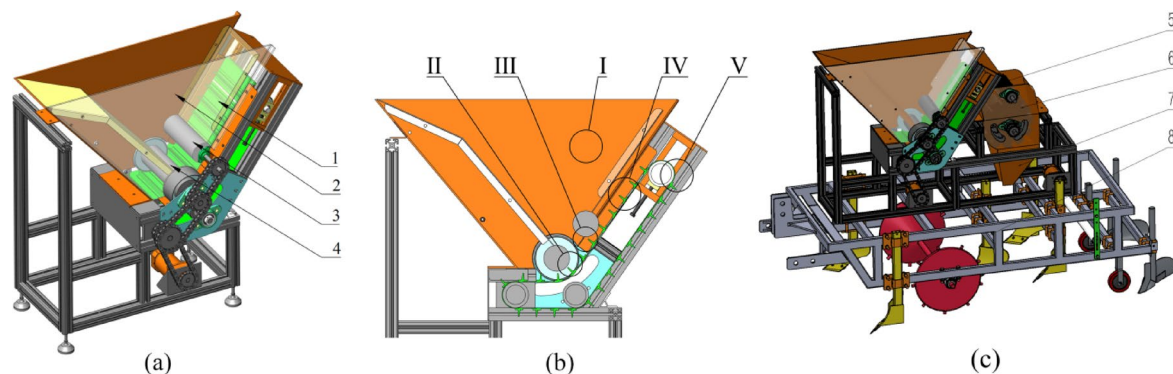
The mechanical and physical characteristics of the *P. hybridum* stems, such as their external dimensions, density, and surface friction properties, differ significantly from those of other crops propagated through pre-cut stems. As a result, existing seed-metering devices are unable to effectively carry out the seeding operations for pre-cut *P. hybridum* stems. Therefore, there is an urgent need to develop a specialized pre-cutting seed stem seed-metering device for *P. hybridum* and to improve its metering performance in order to address key issues such as seed stem jamming, high rates of missed seeding and excessive reseeded. This study is based on the previously developed pre-cut seed-stem sorting, conveying, and seed-metering device for *P. hybridum*. Through single-factor experiments and a quadratic regression orthogonal rotation combination design, the operational parameters of the device's key components were optimized. The goal is to enhance the performance of the seed-metering device, achieve efficient and stable seed metering, and provide a technical reference for advancing the mechanized planting of seed stem crops in China.

## Materials and methods

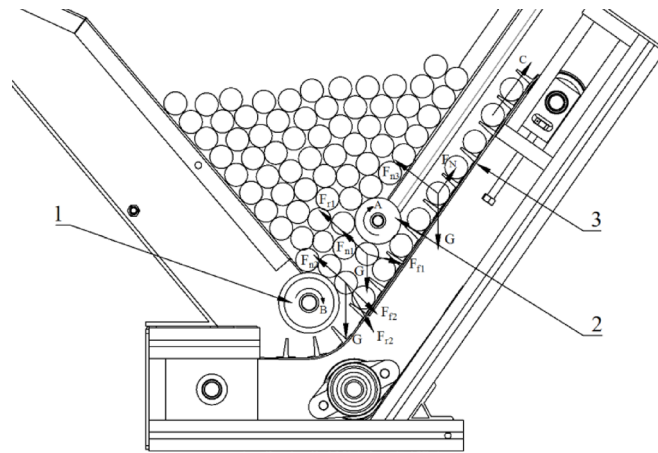
### Overall structure and key components

#### Overall structure and working principle

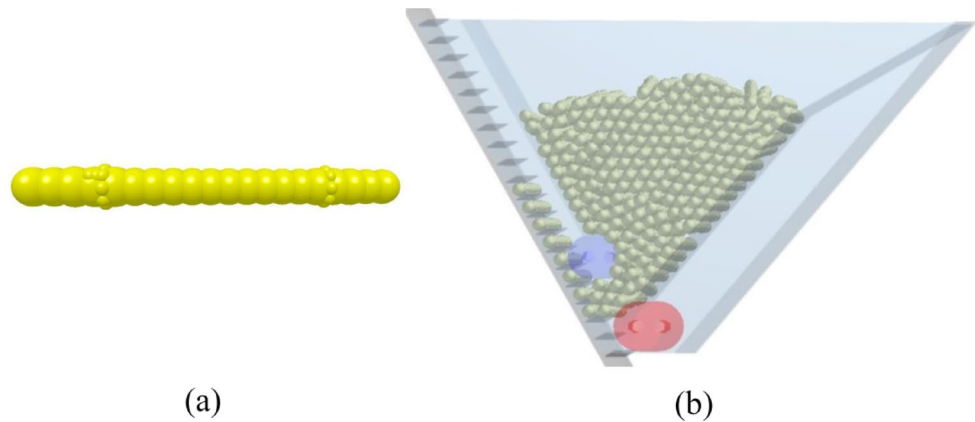
The overall structure of the pre-cut seed-stem seed-metering device for *P. hybridum* is shown in Fig. 1a. It mainly consists of a seed box, seed-filling rubber roller, conveyor belt, seed-cleaning rubber roller, drive system and support frame. The seed-metering device employs a composite operation mode: seed stems are disturbed and filled by friction from the seed-filling rubber roller, conveyed via the belt, and cleaned by the rotating friction of seed-cleaning rubber roller. The workflow is divided into five zones (see Fig. 1b): zone I (Seed Storage), zone II (Seed Filling), zone III (Seed Cleaning), zone IV (Conveying), zone V (Seeding). During the operation, the pre-cut seed stems are placed laterally into the seed storage box of zone I. The motor drives the active roller to operate the conveyor belt, allowing the seed-filling slots to rotate and engage the seed stems. As the seed stems enter zone II, they are embedded into the slots under the combined effects of the tangential friction from the seed-filling roller, inter-stem pressure, and the slot support force. When reaching zone III, the seed-cleaning rubber roller removes excess seed stems (falling back to zone I) through friction and gravity; a parallel seed-blocking plate above the roller prevents seed stems from rolling back into the seed filling slots. The seed stems are transported to the highest point in zone IV and then enter zone V, where they are finally discharged under the action of gravity. After seed stems are discharged from the seed-metering device, they enter the fluted roller



**Fig. 1.** Three-dimensional drawing of the seed-metering device: (a) Overall structure; (b) Working principle; (c) General assembly 3D drawing, with 1. Conveyor belt, 2. Seed box, 3. Seed-cleaning rubber roller, 4. Seed-filling rubber roller, 5. Brush, 6. Seed-metering fluted roller, 7. Seed-guiding plate, 8. Furrowing and ridging base; I. Seed-storage zone, II. Seed-filling zone, III. Seed-cleaning zone, IV. Conveying zone, V. Seeding zone.



**Fig. 2.** Force analysis diagram of the seed stem: 1. Seed-filling rubber roller, 2. Seed-cleaning rubber roller, 3. Conveyor belt; (A) Seed-cleaning rubber roller rotation speed, (B) Seed-filling rubber roller rotation speed, (C) Conveyor belt operating speed.



**Fig. 3.** Simulation model: (a) Discrete element model of seed stem; (b) Model of seeding device.

conveying device (see Fig. 1c, which is mainly composed of a brush, a seed-metering fluted roller, and a seed-guiding plate). As the seed-metering fluted roller rotates, the seed stems embed into its grooves, and precision seeding is achieved under the cleaning effect of the brush. Subsequently, the seed stems slide out along the seed guiding plate; with a fixed posture, they are ensured to fall into the furrow created by the furrowing and ridging base directly below, thus completing the seeding operation.

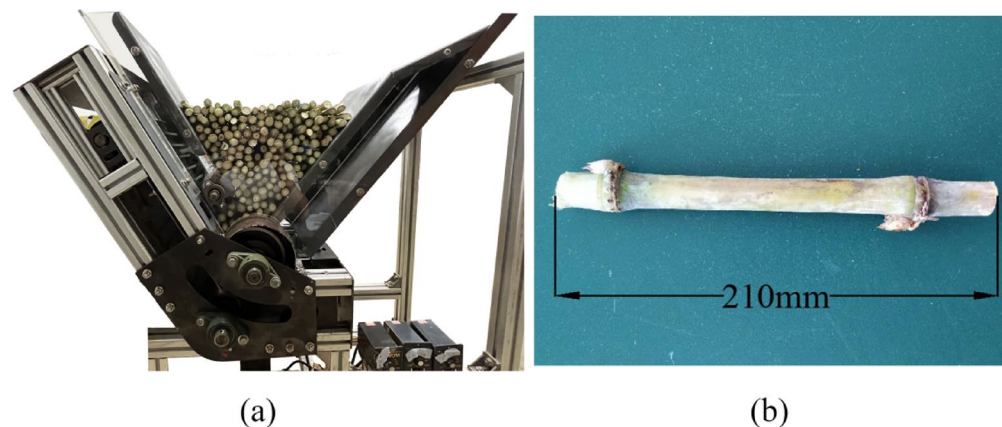
#### Key components and key operational parameters

The seed-metering device completes the metering process through the combined actions of seed-filling rubber roller (for seeds filling), the seed-cleaning rubber roller (for seeds cleaning), and the conveyor belt (for seed stem transport). The force analysis of seed stems during seed filling, clearing, and transporting stages at any given moment (as shown in Fig. 2) reveals that varying the speed of any component—the seed-filling rubber roller, seed-cleaning rubber roller, or conveyor belt—alters the disturbance force and the flow behavior of the seed stems. These changes directly affect the seed-filling and seed-clearing performance, thereby impacting the overall seed-metering efficiency. Therefore, it is determined that the seed-cleaning rubber roller, the seed-filling rubber roller, and the conveyor belt are the key components affecting the performance of the *P. hybridum* seed-metering device.

Initial test values (70 r/min for seed-cleaning rubber roller rotation speed, 25 r/min for seed-filling rubber roller rotation speed, and 0.05 m/s for conveyor belt operating speed) for each key operational parameters were established through reviewing relevant references and theoretical analysis of this study. Using these values as midpoints, simulation preliminary tests were conducted at specific gradient. The simulation model is shown in Fig. 3. It can be seen from the simulation-based preliminary tests<sup>20</sup> that if the seed-cleaning rubber roller rotates too lowly (below 50 r/min), it fails to effectively remove excess seed stems, while excessively high rotation speeds (above 90 r/min) forcibly dislodge qualified seed stems, reducing the seeding qualification rate. Similarly, insufficient rotation speed (below 17 r/min) of the seed-filling rubber roller leads to untimely seed filling and causes missed seeding, whereas an excessively high speed (above 29 r/min) causes the accumulation of seed

Experimental factors	Seed-cleaning rubber roller rotation speed/(r min <sup>-1</sup> )	Seed-filling rubber roller rotation speed/(r min <sup>-1</sup> )	Conveyor belt operating speed/(m s <sup>-1</sup> )
Value range	50~90	17~29	0.03~0.07

**Table 1.** The value range of key operational parameters.



**Fig. 4.** Experimental device and material: (a) Experiment bench; (b) Seed stems of *P. hybridum*.

stems, resulting in reseeded; The speed of conveyor belt simultaneously affects the performance of both seed-filling and seed-cleaning rubber rollers. Moreover, excessively low speed will severely impair the operational efficiency of the seed-metering device. Therefore, the rotation speed of seed-cleaning and seed-filling rubber rollers, and the operating speed of the conveyor belt are the key operational parameters. With a forward machine speed of 0.8 m/s, based on the results of simulation tests and comprehensive considerations, the recommended parameter ranges for these key components are shown in Table 1.

#### Experimental device and material

Experimental device and material are shown in Fig. 4. The experimental apparatus was powered by three 6GU-40K variable-speed stepper motors (each with a rated power of 200 W), which drove the chain shafts. Prior to testing, the speed of each chain shaft was calibrated using a DELIXI 880 laser digital tachometer. The test material is the cultivar “Reyan No. 4”<sup>21</sup>. A total of 200 seed stems with uniform specifications (length: 210mm; average diameter: 19.79 mm; small curvature) were randomly selected for experiments.

#### Experimental factors and evaluation indexes

The experimental factors included the seed-cleaning rubber roller rotation speed (A), the seed-filling rubber roller rotation speed (B) and the conveyor belt operating speed (C). In accordance with the agronomic requirements and with reference to the national standard GB/T6973-2005 “Testing methods of single seed drills (precision drills)”<sup>22</sup>, the seed-metering qualified rate  $Y_1$ , the missed seeding rate  $Y_2$ , and the reseeded rate  $Y_3$  were taken as the evaluation indices, and the calculation method as presented in Eq. (1).

$$\begin{aligned}
 Y_1 &= \frac{n_1}{N} \times 100\% \\
 Y_2 &= \frac{n_2}{N} \times 100\% \\
 Y_3 &= \frac{n_3}{N} \times 100\%
 \end{aligned}
 \tag{1}$$

where  $n_1$  is the total number of holes with 0 seed;  $n_2$  is the total number of holes with 1 seed;  $n_3$  is the total number of holes with 2 or more seeds;  $N$  is the theoretical number of seeding holes.

#### Experimental plan

##### Single factor experimental plan

Based on the selected parameter range and experimental design, the factor level gradient for each test factors are shown in Table 2. During the experiment, 200 seed stems were sequentially placed in the seed box. The seed-filling rubber roller, seed-cleaning rubber roller and conveyor belt were driven by independent motors. The testing process was as follows: firstly, the driving motor for the seed-filling and seed-clearing rubber rollers were activated; once the filling area was fully loaded, the conveyor belt motor was engaged to begin transporting seed stems; the seed-metering process was monitored in real time and relevant data were recorded; after all seed stems were discharged, all power units were shut down. Each factor-level combination was repeated three times and labeled for traceability. A high-speed camera continuously recorded the seed seem movement trajectories. Image

Experimental factors	Seed-cleaning rubber roller rotation speed/(r min <sup>-1</sup> )	Seed-filling rubber roller rotation speed/(r min <sup>-1</sup> )	Conveyor belt operating speed/(m s <sup>-1</sup> )
Level gradient	50	17	0.03
	60	20	0.04
	70	23	0.05
	80	26	0.06
	90	29	0.07

**Table 2.** The level gradient of experimental factors.

Coded value	Factor level		
	Seed-cleaning rubber roller rotation speed/(r min <sup>-1</sup> )	Seed-filling rubber roller rotation speed/(r min <sup>-1</sup> )	Conveyor belt operating speed/(m s <sup>-1</sup> )
-1.682	60.0	23.0	0.030
-1	64.1	24.2	0.034
0	70.0	26.0	0.040
+1	76.0	27.8	0.046
+1.682	80.0	29.0	0.050

**Table 3.** Factor level table.

analysis and data processing were then employed to identify the influence patterns of each parameter on seed-metering performance<sup>23,24</sup>. The single-factor experiments were conducted to explore the effects of individual parameters on metering performance, determine the optimal parameter ranges, and lay the foundation for the subsequent orthogonal experimental design.

#### *Quadratic regression orthogonal rotational combination experimental plan*

In order to further analyze the influence of each parameter on seed-metering performance, a three-factor, five-level quadratic regression orthogonal rotational combination experiment was carried out, on the basis of the results of the single-factor analysis, and following the principles of the Central Composite Design using Design-Expert software<sup>25</sup>. The experimental procedure was consistent with that of single factor experiments, and the factor levels were shown in Table 3.

Regression fitting analysis of the experimental data was conducted using Design-Expert 12 software<sup>26–30</sup> to establish quadratic polynomial regression models. The significance tests were then conducted to evaluate the degree of interaction among the experimental factors and their influence on the performance indicators.

The effects of pairwise interaction among factors A, B and C on response variables  $Y_1$ ,  $Y_2$  and  $Y_3$  were analyzed by Central Composite response surface method in Design-Expert software. By holding one factor at its median level and varying the other two, the response surface diagrams<sup>31–34</sup> illustrating the interaction effects on the evaluation indices were obtained.

## Results and discussion

### Experimental results and analysis

#### *Single factor experimental results and analysis*

According to the single-factor experiment plan, a total of 15 test groups were conducted, with each group replicated three times. The results were averaged as shown below.

As shown in Fig. 5, with the increasing rotation speed of the seed-cleaning rubber roller, the qualified seed-metering rate first rose and then fell. When the rotation speed of the seed-cleaning rubber roller ranged from 50 to 70 r/min, the increase in speed facilitated a dynamic balance in seed-filling zone, effectively preventing the accumulation of seed stems while ensuring the stable filling. The qualified metering rate reached its peak at 70 r/min, accompanied by the lowest missed seeding and a relatively low reseeding rate. When the rotation speed of the seed-cleaning rubber roller exceeded 80 r/min, the excessive centrifugal force caused some previously filled seed stems to be forcibly dislodged. At 90 r/min, the fluidization effect was significantly enhanced, leading to a decline in the qualified metering rate and a simultaneous increase in both the missed seeding and the reseeding rates.

The results of the single factor experiment on the seed-filling rubber roller speed (Fig. 6) show that the qualified metering rate increased first and then decreased with the increasing roller speed. When the seed-filling rubber roller speed increased within the range of 17~26 r/min, the agitation effect on the seed stems was enhanced, making it easier for seed stems to enter into the seed-filling slots. As a result, the qualified rate improved—reaching its maximum at 26 r/min—while the missed seeding rate decreased. However, with the improving seed-filling performance, the seed-filling slot was easy to be filled with smaller seed stems, leading to a rise in the reseeding rate. When the seed-filling rubber roller speed exceeded 26 r/min, excessive centrifugal force caused severe accumulation of seed stems, significantly increasing the reseeding rate and decreasing the qualified metering rate.

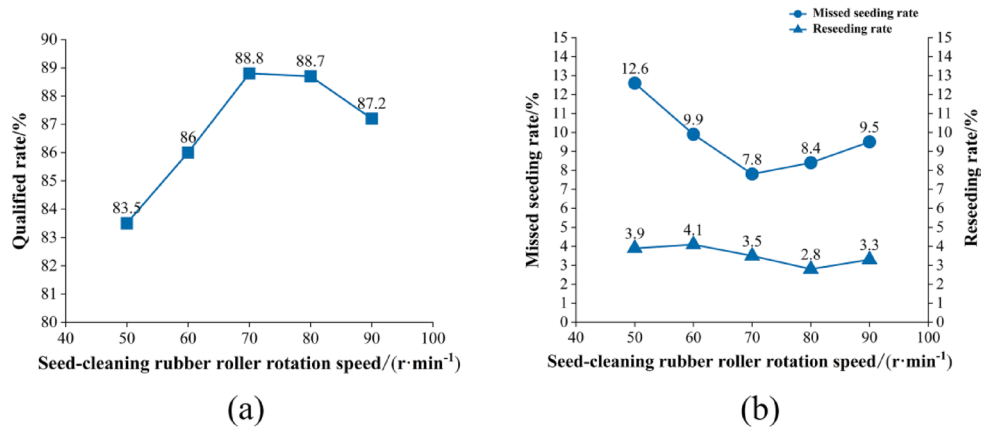


Fig. 5. Effect curve of seed-cleaning rubber roller rotation speed on seeding performance indicators: (a) Qualified rate; (b) Missed seeding rate and Reseeding rate.

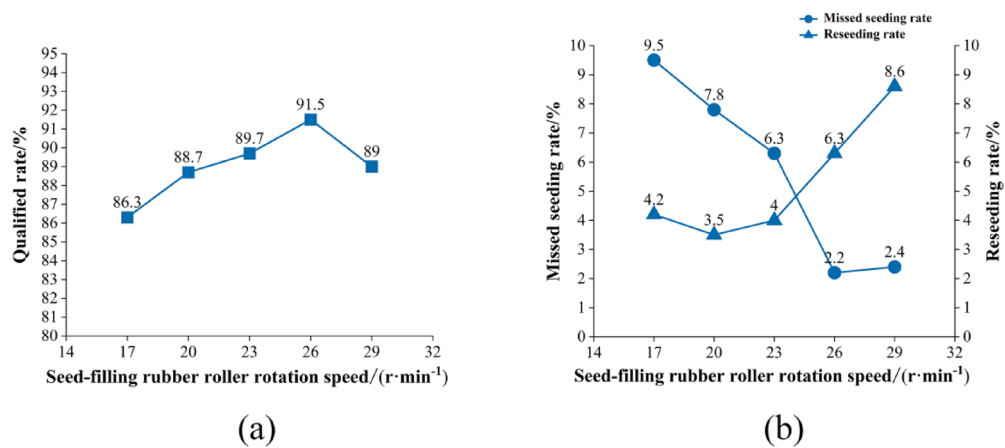


Fig. 6. Effect curve of seed-filling rubber roller rotation speed on seeding performance indicators: (a) Qualified rate; (b) Missed seeding rate and Reseeding rate.

The results of the single factor experiment on conveyor belt operating speed, as shown in Fig. 7, indicate that when the rotation speed of seed-cleaning and seed-filling rubber rollers remained constant, an increase in conveyor belt speed led to a weakening of both seed-filling and seed-cleaning effects, especially the filling performance. Therefore, with the increase of conveyor belt operating speed, the qualified metering rate decreased continuously, while the missed seeding rate greatly increased. Due to the progressively reduced seed-filling effectiveness, fewer seed stems were retained in the filling slots, leading to a gradual decline in the reseeded rate.

*Quadratic regression orthogonal rotational combination experiment results*

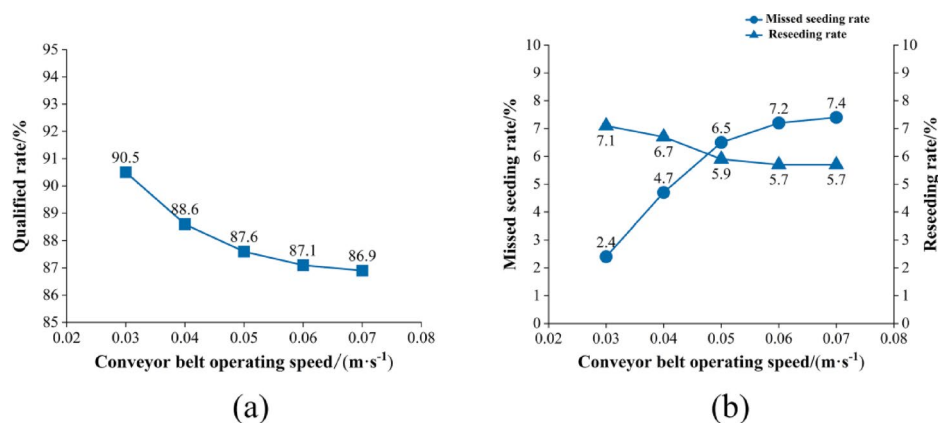
A total of 23 experimental runs were conducted, and the results are shown in Table 4.

**Regression model establishment and analysis of variance**

Based on the analysis results, the regression models describing the relationships between the qualified seed-metering rate, missed seeding rate, reseeded rate, and the experimental factors were obtained as presented in Eq. (2).

$$\begin{aligned}
 Y_1 &= 90.14 - 0.69A - 0.66B + 0.48C + 1.29AB + 0.37AC - 0.30BC - 1.02A^2 - 0.24B^2 - 0.36C^2 \\
 Y_2 &= 3.93 + 0.32A + 0.45B - 0.48C - 0.58AB - 0.06AC + 0.58BC + 0.07A^2 + 0.09B^2 + 0.18C^2 \quad (2) \\
 Y_3 &= 5.92 - 0.37A + 0.21B - 0.01C - 0.71AB - 0.31AC - 0.27BC + 0.96A^2 + 0.16B^2 + 0.19C^2
 \end{aligned}$$

The analysis results of variance are shown in Tables 5, 6 and 7. All regression models exhibited statistically significant goodness of fit ( $P < 0.05$ ), confirming that the models effectively represent the correlations among the variables. The lack-of-fit test results showed  $P$ -values greater than 0.05, indicating that the model did not omit significant factor, and the regression models were well fitted. Reliability analysis (Table 8) further validated the robustness of the models. The coefficients of variation and adjusted coefficients of determination demonstrated



**Fig. 7.** Effect curve of conveyor belt operating speed on seeding performance indicators: (a) Qualified rate; (b) Missed seeding rate and Reseeding rate.

Experiment number	Factor level			Evaluation indicators		
	Seed-cleaning rubber roller rotation speed/(r min <sup>-1</sup> )	Seed-filling rubber roller rotation speed/(r min <sup>-1</sup> )	Conveyor belt operating speed/(m s <sup>-1</sup> )	Qualified rate Y <sub>1</sub> /%	Missed seeding rate Y <sub>2</sub> /%	Reseeding rate Y <sub>3</sub> /%
1	-1	-1	-1	89.82	3.71	6.47
2	1	-1	-1	86.53	5.72	7.75
3	-1	1	-1	88.36	4.32	7.32
4	1	1	-1	87.77	4.41	7.82
5	-1	-1	1	91.74	2.13	6.13
6	1	-1	1	87.48	4.31	8.21
7	-1	1	1	86.62	5.45	7.93
8	1	1	1	89.95	4.91	5.14
9	-1.682	0	0	88.59	3.8	7.61
10	1.682	0	0	85.88	4.15	9.97
11	0	-1.682	0	91.29	3.17	5.55
12	0	1.682	0	87.63	4.88	7.49
13	0	0	-1.682	88.14	5.83	6.04
14	0	0	1.682	90.1	2.73	7.17
15	0	0	0	89.12	4.32	6.56
16	0	0	0	89.35	3.82	6.83
17	0	0	0	90.64	4.13	5.23
18	0	0	0	90.71	3.76	5.43
19	0	0	0	89.61	4.57	5.82
20	0	0	0	88.63	4.68	6.69
21	0	0	0	91.55	3.68	4.77
22	0	0	0	91.62	2.64	5.74
23	0	0	0	90.04	3.84	6.12

**Table 4.** Experimental results.

that the models can effectively capture the influence patterns of the experimental factors on the performance indicators. Therefore, these regression models can be reliably used to analyze the effects of each factor and to predict the optimal combination of working parameters.

As shown in Table 5, the linear terms for the seed-cleaning rubber roller speed (A) and the seed-filling rubber roller speed (B) had a significant influence on the qualified seed-metering rate ( $P < 0.05$ ), while the conveyor belt operating speed (C) had no significant influence ( $P > 0.05$ ). The order of influence of the primary factors was  $A > B > C$ . Among the second-order interaction terms, AB exhibited a highly significant influence on the qualified rate ( $P < 0.01$ ), whereas AC and BC were not significant ( $P > 0.05$ ). The influence of the interaction terms followed the order of  $AB > AC > BC$ .

As shown in Table 6, the linear terms for the seed-filling rubber roller speed (B) and the conveyor belt speed (C) had significant effects on the missed seeding rate ( $P < 0.05$ ), whereas the seed-cleaning rubber roller speed (A) had no significant influence ( $P > 0.05$ ). The primary factors influencing the missed seeding rate ranked in the

Source of Variance	Sum of squares	Degrees of freedom	Mean square	F	P
Model	50.03	9	5.56	5.17	0.0041
A	6.43	1	6.43	5.98	0.0295
B	5.96	1	5.96	5.55	0.0349
C	3.20	1	3.20	2.97	0.1084
AB	13.24	1	13.24	12.31	0.0038
AC	1.09	1	1.09	1.01	0.3328
BC	0.7381	1	0.7381	0.6866	0.4223
A <sup>2</sup>	16.63	1	16.63	15.47	0.0017
B <sup>2</sup>	0.8869	1	0.8869	0.8250	0.3802
C <sup>2</sup>	2.02	1	2.02	1.88	0.1937
Residual	13.98	13	1.08		
Lack of fit	4.99	5	0.9973	0.8876	0.5312
Pure error	8.99	8	1.12		
Total	64.01	22			

**Table 5.** Analysis of qualified index variance of regression equation.

Source of variance	Sum of squares	Degrees of freedom	Mean square	F	P
Model	12.64	6	2.11	5.37	0.0033
A	1.37	1	1.37	3.50	0.0798
B	2.72	1	2.72	6.94	0.0180
C	3.16	1	3.16	8.07	0.0118
AB	2.69	1	2.69	6.86	0.0186
AC	0.0264	1	0.0264	0.0674	0.7984
BC	2.67	1	2.67	6.80	0.0190
A <sup>2</sup>	0.0747	1	0.0747	0.1736	0.6837
B <sup>2</sup>	0.1182	1	0.1182	0.2747	0.6090
C <sup>2</sup>	0.4945	1	0.4945	1.15	0.3033
Residual	6.27	16	0.3922		
Lack of fit	3.34	8	0.4169	1.13	0.4312
Pure error	2.94	8	0.3674		
Total	18.92	22			

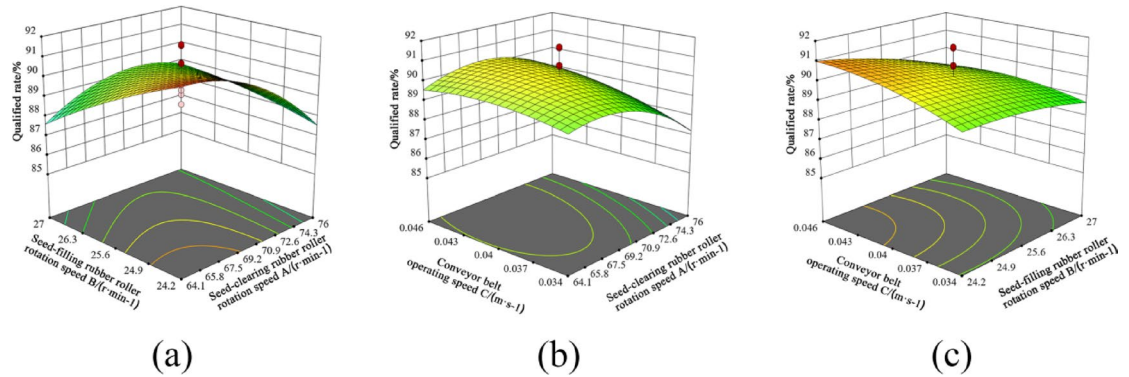
**Table 6.** Variance analysis of missed seeding index of regression equation.

Source of variance	Sum of squares	Degrees of freedom	Mean square	F	P
Model	23.26	9	2.58	3.44	0.0218
A	1.86	1	1.86	2.47	0.1399
B	0.6212	1	0.6212	0.8262	0.3799
C	0.0002	1	0.0002	0.0002	0.9879
AB	3.99	1	3.99	5.31	0.0384
AC	0.7750	1	0.7750	1.03	0.3285
BC	0.5995	1	0.5995	0.7973	0.3881
A <sup>2</sup>	14.56	1	14.56	19.37	0.0007
B <sup>2</sup>	0.3809	1	0.3809	0.5066	0.4892
C <sup>2</sup>	0.5432	1	0.5432	0.7224	0.4108
Residual	9.77	13	0.7519		
Lack of fit	5.82	5	1.16	2.36	0.1345
Pure error	3.95	8	0.4939		
Total	33.03	22			

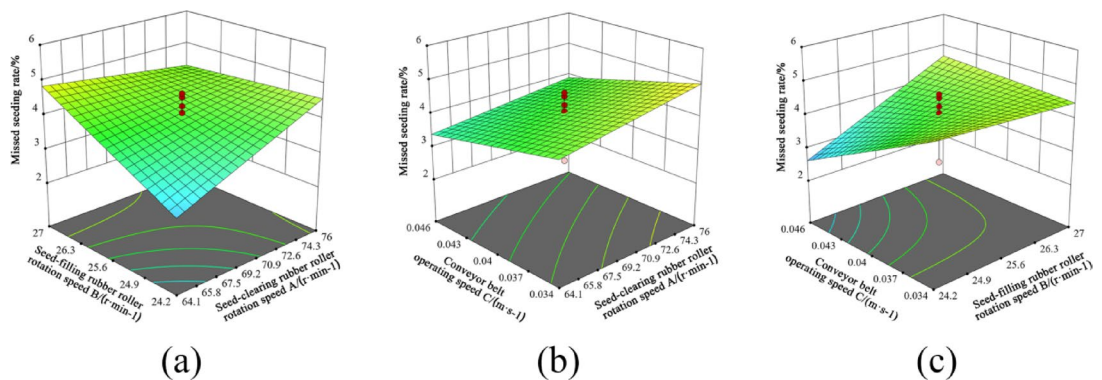
**Table 7.** Regression equation reseeding index variance analysis.

Response	Coefficient of variation/%	Goodness-of-fit	Correction coefficient of determination	SNR
$Y_1$	1.16	0.7817	0.6305	8.0731
$Y_2$	15.89	0.7043	0.4995	9.0429
$Y_3$	12.97	0.7041	0.4992	6.8230

**Table 8.** Reliability analysis of regression model.



**Fig. 8.** Influence of interactive factors on the qualified rate of seeding: (a)  $C = 0.04$  m/s; (b)  $B = 26$  r/min; (c)  $A = 70$  r/min.



**Fig. 9.** Influence of interactive factors on missed seeding rate of seeding: (a)  $C = 0.04$  m/s; (b)  $B = 26$  r/min; (c)  $A = 70$  r/min.

order of  $C > B > A$ . Among the second-order interaction terms, AB and BC had a significant influence on the missed seeding rate ( $P < 0.05$ ), while AC was not significant ( $P > 0.05$ ). The order of influence among the interaction terms was  $AB > BC > AC$ .

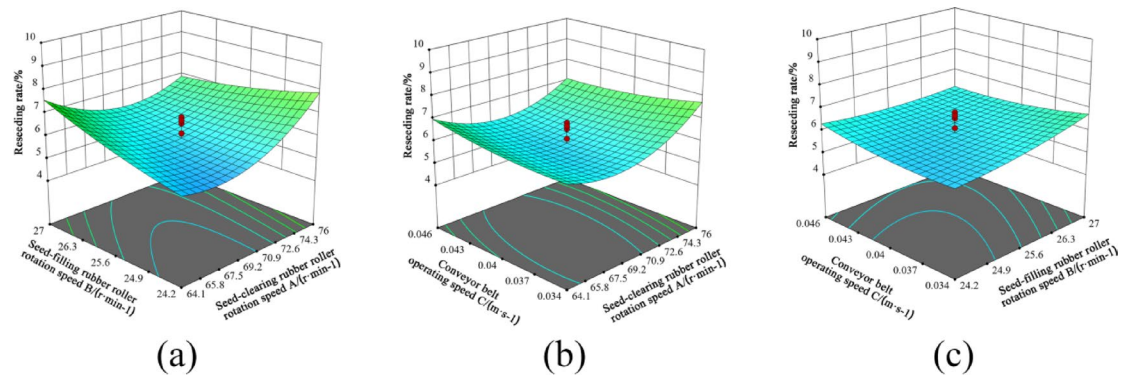
As shown in Table 7, the primary factors affecting the reseeding rate ranked in the order of  $A > B > C$ . Among the second-order interaction terms, AB had a significant influence on the reseeding rate ( $P < 0.05$ ). The influence of the interaction terms ranked as  $AB > AC > BC$ .

### Response surface analysis

The response surface diagrams illustrating the interaction effects on the evaluation indices as shown in Fig. 8, 9 and 10.

Figure 8 shows the response surfaces illustrating the influence of each interaction factor on the qualified metering rate. As shown in Fig. 8a, the qualified rate decreased with the increase in both seed-cleaning and seed-filling rubber roller rotation speeds. The qualified rate remained at a higher level when both speeds are relatively low, indicating that these two parameters exert a significant influence on the qualified rate. In Fig. 8b, the qualified rate increased first and then decreased as the speeds of seed-cleaning and the seed-filling rubber rollers increase. In Fig. 8c, the qualified rate consistently decreased with the increase in the seed-filling rubber roller speed and the decrease in the conveyor belt speed.

Figure 9 shows the response surface of the influence of each interaction factor on the missed seeding rate. As shown in Fig. 9a, the missed seeding rate increased linearly with increasing seed-cleaning and seed-filling rubber



**Fig. 10.** Influence of interactive factors on reseeding rate of seeding: (a)  $C = 0.04$  m/s; (b)  $B = 26$  r/min; (c)  $A = 70$  r/min.

roller rotation speeds, The rate of increase is nearly identical along both axes, showing no obvious difference in their influence on the missed seeding rate. As shown in Fig. 9b, the missed seeding rate increased with the increase in the seed-clearing rubber roller speed and the decrease in the conveyor belt speed. The lowest missed seeding rate was observed when the seed-clearing rubber roller speed was at its minimum and the conveyor belt speed was at its maximum. As shown in Fig. 9c, the missed seeding rate increased with the increase in the seed-filling rubber roller speed and the decrease in the conveyor belt speed.

Figure 10 shows the response surface plots of the influence of each interaction factor on the reseeding rate. As shown in Fig. 10a, the reseeding rate decreased initially and then increased with the increases in seed-clearing rubber roller speed and the decreases in the seed-filling rubber roller speed. The lowest re-seeding rate was observed when both speeds were at their minimum values. Figure 10b reveals a similar trend to that in Fig. 10a. The minimum reseeding rate occurred when both speeds were both at intermediate levels. Figure 10c indicates a relatively mild variation in the reseeding rate, with the lowest value occurring when both speeds were low.

### Optimization of experimental results

Based on the above experimental results, the optimal working parameters for the seed-metering device were obtained using the optimization module in Design-Expert. The parameter ranges were set as follows: the seed-clearing rubber roller rotation speed between 60~80 r/min, the seed-filling rubber roller rotation speed between 23~29 r/min, and the conveyor belt operating speed between 0.03~0.05 m/s. Taking the maximum qualified rate and the minimum reseeding and missed seeding rates as the objectives of optimization, the objective function and the factors constraints are defined as presented in Eq. (3).

$$\begin{cases} \max Y_1 \\ \min Y_2 \\ \min Y_3 \\ -1.682 < A < 1.682 \\ -1.682 < B < 1.682 \\ -1.682 < C < 1.682 \end{cases} \quad (3)$$

Based on optimization calculations conducted using the Optimization module in Design-Expert software, the optimal parameter combination was obtained: 62.2 r/min for the seed-clearing rubber roller rotation speed, 23 r/min for the seed-filling rubber roller rotation speed, and 0.045 m/s for the conveyor belt operating speed. Under these conditions, the qualified rate was 92.5%, the missed seeding rate was 2.13%, and the reseeding rate was 5.127%. To ensure the reliability of the optimization results, experimental validation was carried out under the same conditions.

### Bench validation experiment

Consistent with the single-factor test procedure, the bench verification experiment showed that the optimized parameter combination (62.2 r/min for seed-clearing rubber roller rotation speed, 23 r/min for seed-filling rubber roller rotation speed, and 0.045 m/s for conveyor belt operating speed) resulted in the qualified rate of 91.8%, the missed seeding rate of 2.5%, the reseeding rate of 5.7%, and the effective filling rate of 97.5%. These results closely matched the model predictions, with the relative error of only 0.76% in the qualified rate, indicating the reliability of the optimization results.

## Limitations and future prospects of research

### Limitations

- (1) *Limited sample types* This study was only conducted on "Reyan No. 4", its physical characteristics may not be fully representative of other varieties, and its generalizability needs to be further verified.

- (2) *Limitation of working speed* Due to the limitations of the working speed of the seed-metering device (such as the optimal conveyor belt operating speed is 0.045 m/s), the efficiency of the planting operation of *P. hybridum* was limited.
- (3) *Insufficient automation* This study consisted of purely mechanical structures, lacked automatic control, and thus relied on manual labor.

### Future prospects

- (1) *Multi-variety Adaptive Optimization* Extend the experiment to other varieties of *P. hybridum*, and even to other stem crops (such as sugarcane, cassava, etc.), optimize the structure of the seed-metering device, and enhance the versatility of the equipment.
- (2) *Improve the functionality of the seed-metering device* Design and integrate multiple working modules such as rotary tillage & furrowing, soil covering & film mulching, and fertilization systems to enhance the comprehensiveness of the seed-metering device.
- (3) *Intelligent control system development* Through the deep integration of machine vision-based environmental perception and navigation system positioning, the intelligent path planning and automatic driving of the seeder are achieved.

### Conclusions

Single-factor bench tests, response surface optimization tests based on Central Composite Design and bench validation experiments were carried out on the pre-cut stem seed-metering device for *P. hybridum*. The conclusions are as follows:

- (1) Theoretical analysis and preliminary simulation trials identified the key components affecting seeding performance as the seed-cleaning rubber roller, seed-filling rubber roller and conveyor belt. The critical working parameters and their value ranges were determined as follows: seed-cleaning rubber roller rotation speed  $A = 50 \sim 90$  r/min; seed-filling rubber roller rotation speed  $B = 17 \sim 29$  r/min; conveyor belt operating speed  $C = 0.03 \sim 0.07$  m/s.
- (2) The single-factor experiment showed that with the increase in the seed-cleaning rubber roller speed, the qualified seed-metering rate first rose and then fell, reaching the maximum value at 70 r/min, where the lowest value of the missed seeding rate appeared and the reseeding rate was lower. Similarly, with the increase in the seed-filling rubber roller speed, the qualified rate first rose and then fell, peaked at 26 r/min, accompanied by a decrease in the missed seeding rate. With the increase in the conveyor belt operating speed, the qualified rate continuously decreased, and the missed seeding rate was increased substantially.
- (3) Interaction factor analysis of the orthogonal experiment results showed that the primary factors affecting the qualified rate and reseeding were, in order of significance: the seed-cleaning rubber roller rotation speed  $A$ , the seed-filling rubber roller rotation speed  $B$ , and the conveyor belt operating speed  $C$ . For the missed seeding rate, the order of influence was: the conveyor belt operating speed  $C$ , the seed-filling rubber roller rotation speed  $B$ , and the seed-cleaning rubber roller rotation speed  $A$ .
- (4) Parameter optimization was performed using Design-Expert software, the optimal parameter combination was found to be: 62.2 r/min for seed-cleaning rubber roller rotation speed, 23 r/min for seed-filling rubber roller rotation speed, and 0.045m/s for conveyor belt operating speed. Bench verification trials conducted with these optimized parameters yields the qualified rate of 91.8%, the missed seeding rate of 2.5%, the reseeding rate of 5.7%, and the effective seed-filling rate is 97.5%. These results confirm that the optimized pre-cut seed stem seed-metering device meets the operational requirements for seeding performance.

### Data availability

The data supporting this study's findings are available from the corresponding author upon reasonable request.

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## Author contributions

Conceptualization, C.L., X.C., Q.X., M.L. and J.L.; Data curation, C.L.; Formal analysis, C.L. and Y.Z.; Funding acquisition, X.C. and M.L.; Investigation, C.L., Y.Z., C.Z. and Y.X.; Methodology, C.L., X.C., Q.X., M.L., J.L. and J.Y.; Project administration, Q.X. J.L. and J.Y.; Resources, X.C., M.L., J.L., J.Y. and P.F.; Software, C.L.; Supervision, X.C., Q.X. and J.L.; Validation, C.L.; Visualization, Q.X. and J.L.; Writing—original draft, C.L.; Writing—review and editing, C.L., X.C., Q.X., M.L. and J.L. All authors have read and agreed to the published version of the manuscript.

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## Declarations

### Competing interests

The authors declare no competing interests.

### Additional information

**Correspondence** and requests for materials should be addressed to J.L.

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